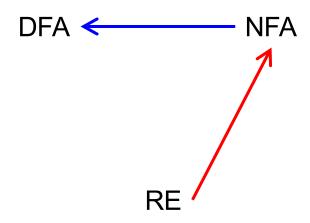
### CMSC 330: Organization of Programming Languages

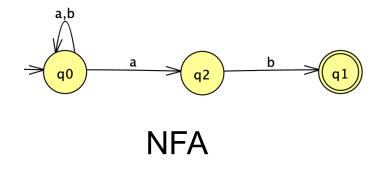
# Reducing NFA to DFA and DFAs Minimization

### Reducing NFA to DFA

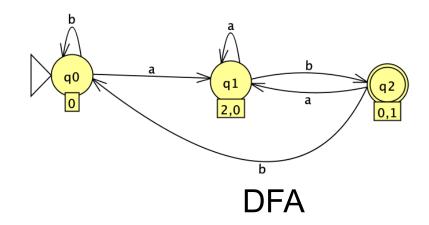


### Why NFA → DFA

DFA is generally more efficient than NFA



Language: (a|b)\*ab



How to accept bab?

### Why NFA → DFA

- DFA has the same expressive power as NFAs.
  - Let language L ⊆ Σ\*, and suppose L is accepted by NFA N = (Σ, Q, q₀, F, δ). There exists a DFA D= (Σ, Q', q'₀, F', δ') that also accepts L. (L(N) = L(D))
- NFAs are more flexible and easier to build. But it is not more powerful than DFAs

## NFA ↔ DFA

### How to Convert NFA to DFA

**Subset Construction Algorithm** 

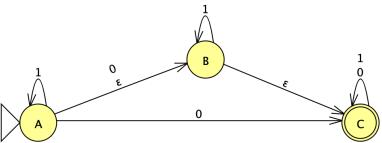
Input NFA ( $\Sigma$ , Q, q<sub>0</sub>, F<sub>n</sub>,  $\delta$ )

Output DFA ( $\Sigma$ , R, r<sub>0</sub>, F<sub>d</sub>,  $\delta$ ')

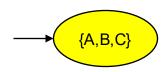
### **Subset Construction Algorithm**

```
Output DFA (\Sigma, R, r<sub>0</sub>, F<sub>d</sub>, \delta')
Input NFA (\Sigma, Q, q<sub>0</sub>, F<sub>n</sub>, \delta)
                      Let r_0 = \varepsilon-closure(\delta, q_0), add it to R
                      While \exists an unmarked state r \in R
                             Mark r
                             For each \sigma \in \Sigma
                             Let E = move(\delta,r,\sigma)
                                   Let e = \varepsilon-closure(\delta,E)
                                   If e ∉ R
                                         Let R = R \cup \{e\}
                                   Let \delta' = \delta' \cup \{r, \sigma, e\}
                      Let F_d = \{r \mid \exists s \in r \text{ with } s \in F_n\}
```

#### NFA



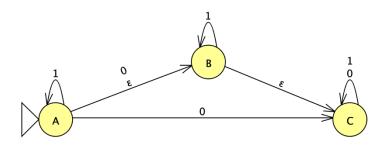
#### **DFA**

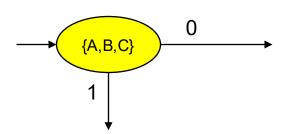


**New Start State** 

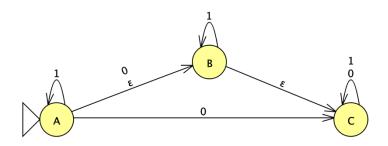
Let  $r_0$  = ε-closure(δ, $q_0$ ), add it to R

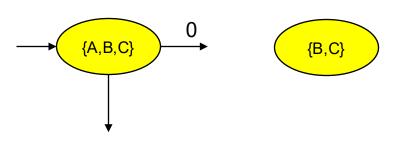
```
Mark r
For each \sigma \in \Sigma
Let E = move(\delta, r, \sigma)
Let e = \epsilon-closure(\delta, E)
If e \notin R
Let R = R \cup {e}
Let \delta' = \delta' \cup \{r, \sigma, e\}
Let F_d = \{r \mid \exists \ s \in r \ with \ s \in F_n\}
```





For each 
$$\sigma \in \Sigma$$
 //0
Let E = move( $\delta, r, \sigma$ )
Let e =  $\epsilon$ -closure( $\delta, E$ )
If e  $\notin R$ 
Let R = R  $\cup$  {e}
Let  $\delta' = \delta' \cup \{r, \sigma, e\}$ 
Let  $F_d = \{r \mid \exists \ s \in r \ with \ s \in F_n\}$ 





	0	1
{A,B,C}	{B,C}	

While  $\exists$  an unmarked state  $r \in R$ 

Mark r

For each  $\sigma \in \Sigma$ 

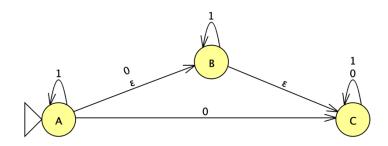
Let E = move( $\delta$ ,r, $\sigma$ )

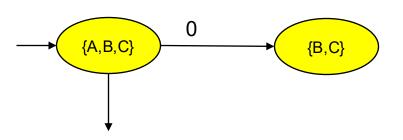
Let e = ε-closure(
$$\delta$$
,E)

If e ∉ R

Let  $R = R \cup \{e\}$ 

Let  $\delta' = \delta' \cup \{r, \sigma, e\}$ 

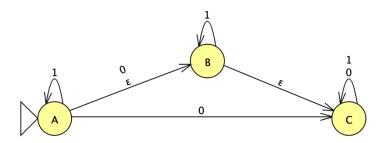


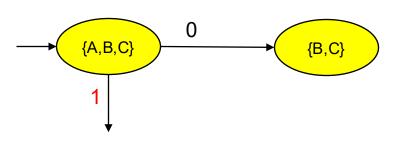


	0	1
{A,B,C}	{B,C}	
{B,C}		

While  $\exists$  an unmarked state  $r \in R$ 

Mark r For each  $\sigma \in \Sigma$ Let E = move( $\delta$ ,r, $\sigma$ ) Let  $e = \varepsilon$ -closure( $\delta$ ,E) If e ∉ R Let  $R = R \cup \{e\}$  $\longrightarrow$  Let  $\delta' = \delta' \cup \{r, \sigma, e\}$ Let  $F_d = \{r \mid \exists s \in r \text{ with } s \in F_n\}$ 





	0	1
{A,B,C}	{B,C}	
{B,C}		

Mark r

For each 
$$\sigma \in \Sigma$$
 //1

Let E = move( $\delta, r, \sigma$ )

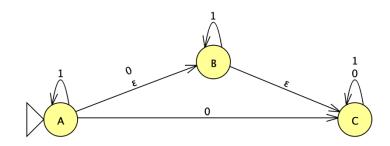
Let e =  $\epsilon$ -closure( $\delta, E$ )

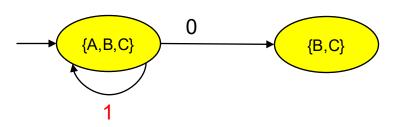
If e  $\notin R$ 

Let R = R  $\cup$  {e}

Let  $\delta' = \delta' \cup \{r, \sigma, e\}$ 

Let  $F_d = \{r \mid \exists \ s \in r \ with \ s \in F_n\}$ 





	0	1
{A,B,C}	{B,C}	{A,B,C}
{B,C}		

For each 
$$\sigma \in \Sigma$$
 //1

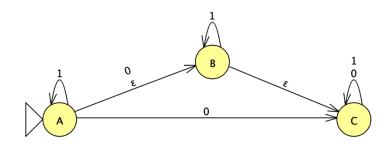
Let E = move(
$$\delta$$
,r, $\sigma$ )

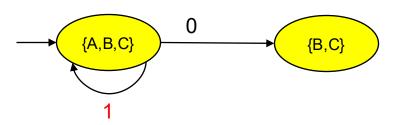
Let e = ε-closure(
$$\delta$$
,E)

Let 
$$R = R \cup \{e\}$$

Let 
$$\delta' = \delta' \cup \{r, \sigma, e\}$$

Let 
$$F_d = \{r \mid \exists s \in r \text{ with } s \in F_n\}$$





_	0	1
{A,B,C}	{B,C}	{A,B,C}
{B,C}		

```
Let r_0 = \epsilon-closure(\delta, q_0), add it to R

While \exists an unmarked state r \in R

Mark r

For each \sigma \in \Sigma //1

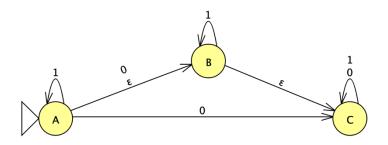
Let E = move(\delta, r, \sigma)

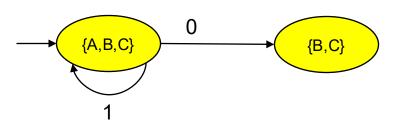
Let e = \epsilon-closure(\delta, E)

If e \notin R

Let R = R \cup \{e\}

Let \delta' = \delta' \cup \{r, \sigma, e\}
```



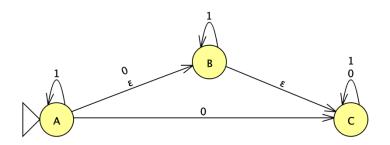


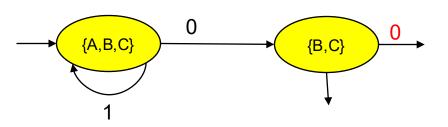
	0	1
{A,B,C}	{B,C}	{A,B,C}
{B,C}		

While  $\exists$  an unmarked state  $r \in R$ Mark rFor each  $\sigma \in \Sigma$  //1

Let  $E = move(\delta, r, \sigma)$ Let  $e = \varepsilon$ -closure( $\delta, E$ )

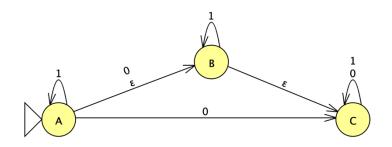
If  $e \notin R$ Let  $R = R \cup \{e\}$ Let  $\delta' = \delta' \cup \{r, \sigma, e\}$ 

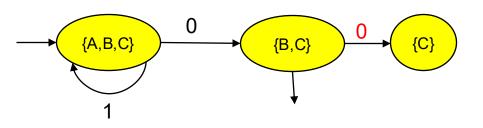




	0	1
{A,B,C}	{B,C}	{A,B,C}
{B,C}		

Mark r
For each 
$$\sigma \in \Sigma$$
 //0
Let E = move( $\delta, r, \sigma$ )
Let e =  $\epsilon$ -closure( $\delta, E$ )
If e  $\notin R$ 
Let R = R  $\cup$  {e}
Let  $\delta' = \delta' \cup \{r, \sigma, e\}$ 
Let  $F_d = \{r \mid \exists \ s \in r \ with \ s \in F_n\}$ 





	0	1
{A,B,C}	{B,C}	{A,B,C}
{B,C}	{C}	

While  $\exists$  an unmarked state  $r \in R$ 

Mark r

For each  $\sigma \in \Sigma$  //0

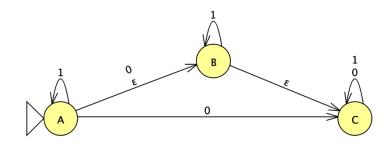
Let E = move( $\delta$ ,r, $\sigma$ )

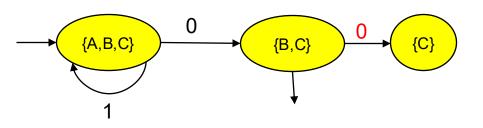
Let e = ε-closure(
$$\delta$$
,E)

If e ∉ R

Let  $R = R \cup \{e\}$ 

Let  $\delta' = \delta' \cup \{r, \sigma, e\}$ 



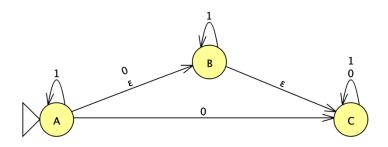


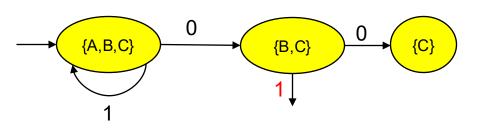
	0	1
{A,B,C}	{B,C}	{A,B,C}
{B,C}	{C}	
{C}		

### Let $r_0 = \epsilon$ -closure( $\delta, q_0$ ), add it to R While $\exists$ an unmarked state $r \in R$

Mark r For each 
$$\sigma \in \Sigma$$
 //0
Let E = move( $\delta, r, \sigma$ )
Let e =  $\epsilon$ -closure( $\delta, E$ )
If e  $\notin R$ 
Let R = R  $\cup$  {e}

Let  $\delta' = \delta' \cup \{r, \sigma, e\}$ 
Let  $F_d = \{r \mid \exists \ s \in r \ with \ s \in F_n\}$ 





_	0	1
{A,B,C}	{B,C}	{A,B,C}
{B,C}	{C}	?
{C}		

For each 
$$\sigma \in \Sigma$$
 //1

Let E = move( $\delta, r, \sigma$ )

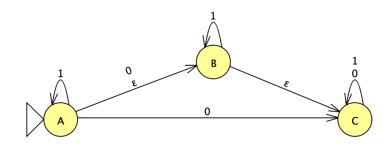
Let e =  $\epsilon$ -closure( $\delta, E$ )

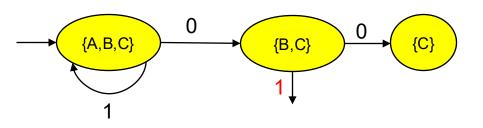
If e  $\notin R$ 

Let R = R  $\cup$  {e}

Let  $\delta' = \delta' \cup \{r, \sigma, e\}$ 

Let  $F_d = \{r \mid \exists \ s \in r \ with \ s \in F_n\}$ 





	0	1
{A,B,C}	{B,C}	{A,B,C}
{B,C}	{C}	{B,C}
{C}		

While  $\exists$  an unmarked state  $r \in R$ 

Mark r

For each  $\sigma \in \Sigma$  //

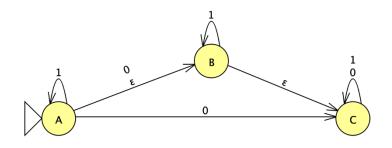
Let E = move( $\delta$ ,r, $\sigma$ )

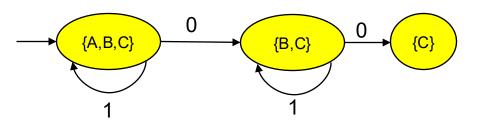
Let e = ε-closure(
$$\delta$$
,E)

If e ∉ R

Let  $R = R \cup \{e\}$ 

Let  $\delta' = \delta' \cup \{r, \sigma, e\}$ 





	0	1
{A,B,C}	{B,C}	{A,B,C}
{B,C}	{C}	{B,C}
{C}		

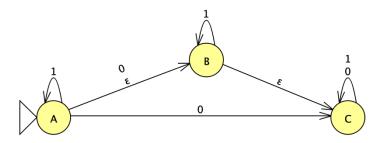
While  $\exists$  an unmarked state  $r \in R$ Mark rFor each  $\sigma \in \Sigma$  //1

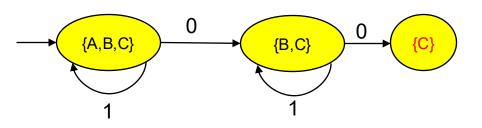
Let  $E = move(\delta, r, \sigma)$ 

Let  $e = \varepsilon$ -closure( $\delta$ ,E) If  $e \notin R$ 

Let  $R = R \cup \{e\}$ 

**Let**  $\delta$ ' =  $\delta$ ' ∪ {r, σ, e}

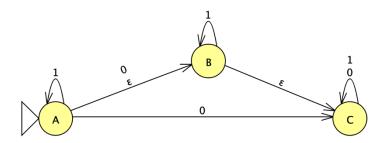


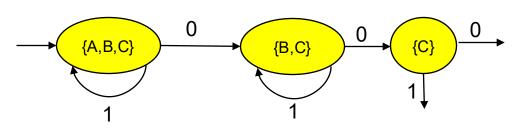


	0	1
{A,B,C}	{B,C}	{A,B,C}
{B,C}	{C}	{B,C}
{C}		

While  $\exists$  an unmarked state  $r \in R$ 

Mark r
For each 
$$\sigma \in \Sigma$$
 //1
Let E = move( $\delta$ ,r, $\sigma$ )
Let e =  $\epsilon$ -closure( $\delta$ ,E)
If e  $\notin$  R
Let R = R  $\cup$  {e}
Let  $\delta$ ' =  $\delta$ '  $\cup$  {r,  $\sigma$ , e}





$$\longrightarrow$$
 For each  $\sigma \in \Sigma$ 

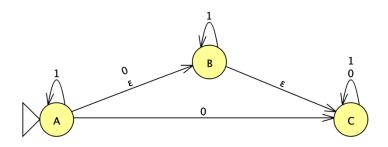
Let E = move(
$$\delta$$
,r, $\sigma$ )

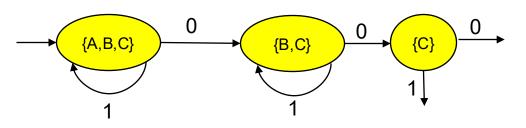
Let 
$$e = \varepsilon$$
-closure( $\delta$ ,E)

Let 
$$R = R \cup \{e\}$$

Let 
$$\delta' = \delta' \cup \{r, \sigma, e\}$$

Let 
$$F_d = \{r \mid \exists s \in r \text{ with } s \in F_n\}$$





	0	1
{A,B,C}	{B,C}	{A,B,C}
{B,C}	{C}	{B,C}
{C}	{C}	

While  $\exists$  an unmarked state  $r \in R$ 

Mark r

For each  $\sigma \in \Sigma$  //0

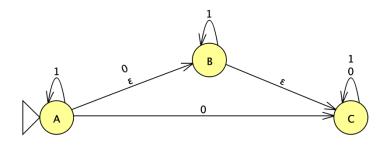
Let E = move( $\delta$ ,r, $\sigma$ )

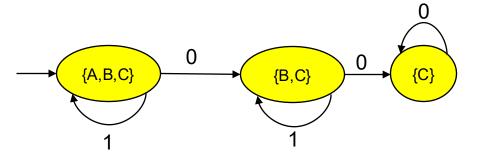
Let e = ε-closure(
$$\delta$$
,E)

If e ∉ R

Let  $R = R \cup \{e\}$ 

Let  $\delta' = \delta' \cup \{r, \sigma, e\}$ 

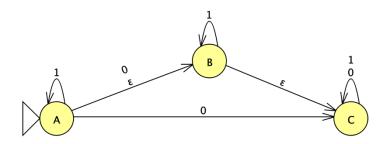


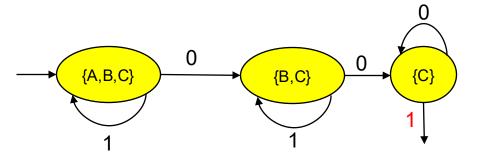


	0	1
{A,B,C}	{B,C}	{A,B,C}
{B,C}	{C}	{B,C}
{C}	{C}	

Let  $r_0 = \epsilon$ -closure( $\delta, q_0$ ), add it to R While  $\exists$  an unmarked state  $r \in R$ Mark rFor each  $\sigma \in \Sigma$  //0 Let E = move( $\delta, r, \sigma$ )

Let E = move(
$$\delta$$
,r, $\sigma$ )  
Let e =  $\epsilon$ -closure( $\delta$ ,E)  
If e  $\notin$  R  
Let R = R  $\cup$  {e}  
Let  $\delta$ ' =  $\delta$ '  $\cup$  {r,  $\sigma$ , e}





	0	1
{A,B,C}	{B,C}	{A,B,C}
{B,C}	{C}	{B,C}
{C}	{C}	

For each 
$$\sigma \in \Sigma$$
 //1

Let E = move( $\delta, r, \sigma$ )

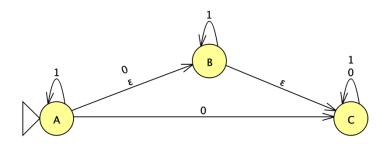
Let e =  $\epsilon$ -closure( $\delta, E$ )

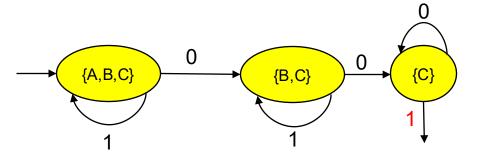
If e  $\notin R$ 

Let R = R  $\cup$  {e}

Let  $\delta' = \delta' \cup \{r, \sigma, e\}$ 

Let  $F_d = \{r \mid \exists \ s \in r \ with \ s \in F_n\}$ 





	0	1
{A,B,C}	{B,C}	{A,B,C}
{B,C}	{C}	{B,C}
{C}	{C}	{C}

For each 
$$\sigma \in \Sigma$$
 //1

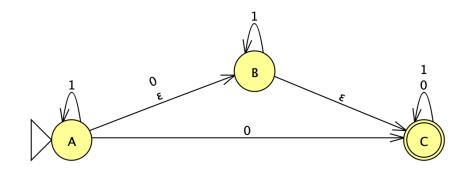
Let E = move(
$$\delta$$
,r, $\sigma$ )

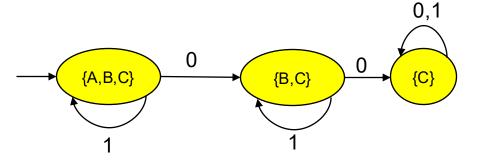
Let e = ε-closure(
$$\delta$$
,E)

Let 
$$R = R \cup \{e\}$$

Let 
$$\delta' = \delta' \cup \{r, \sigma, e\}$$

Let 
$$F_d = \{r \mid \exists s \in r \text{ with } s \in F_n\}$$



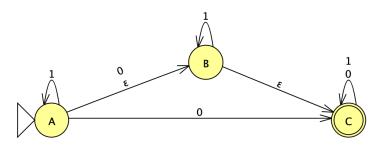


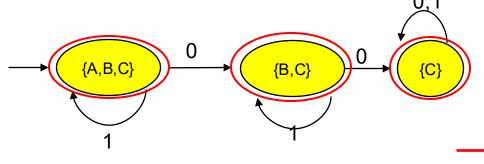
	0	1
{A,B,C}	{B,C}	{A,B,C}
{B,C}	{C}	{B,C}
{C}	{C}	{C}

Mark r
For each 
$$\sigma \in \Sigma$$
 //1
Let E = move( $\delta$ ,r, $\sigma$ )
Let e =  $\epsilon$ -closure( $\delta$ ,E)
If e  $\notin$  R
Let R = R  $\cup$  {e}

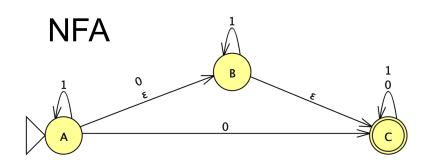
Let  $\delta$ ' =  $\delta$ '  $\cup$  {r,  $\sigma$ , e}

Let 
$$F_d = \{r \mid \exists s \in r \text{ with } s \in F_n\}$$

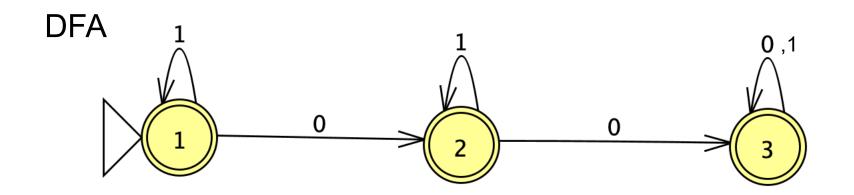


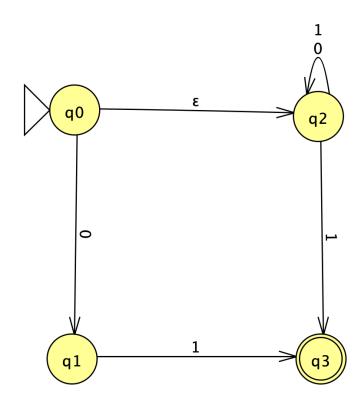


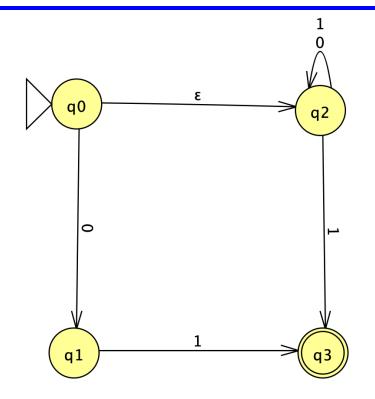
	0	1
{A,B,C}	{B,C}	{A,B,C}
{B,C}	{C}	{B,C}
{C}	{C}	{C}

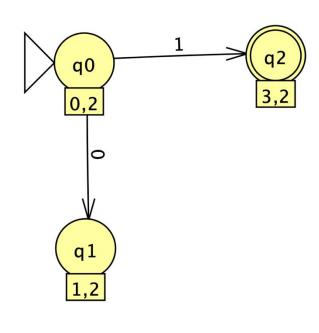


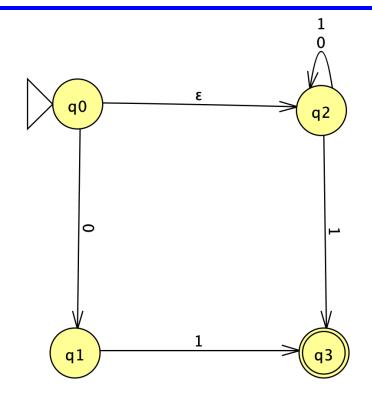
	0	1
{A,B,C}	{B,C}	{A,B,C}
{B,C}	{C}	{B,C}
{C}	{C}	{C}

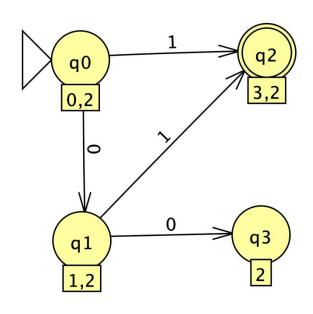


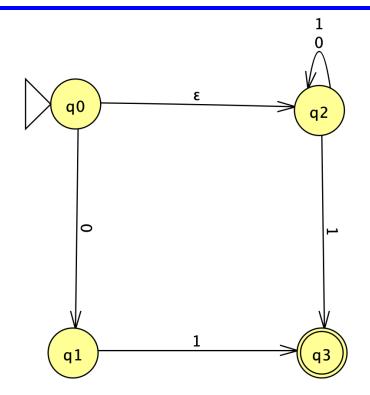


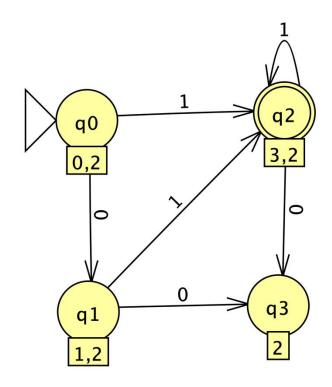


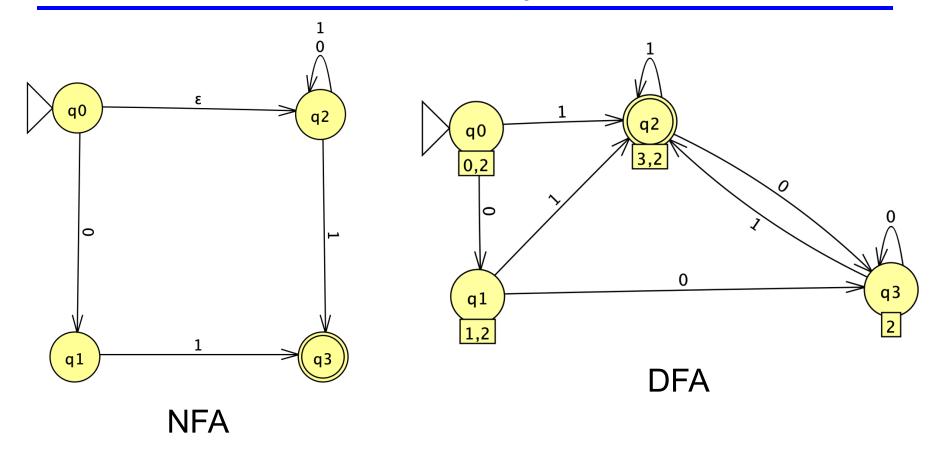




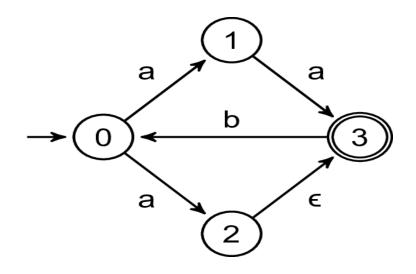




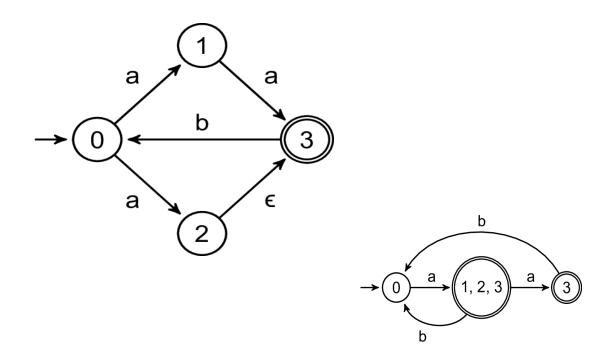




### NFA → DFA Practice

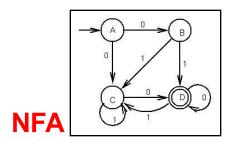


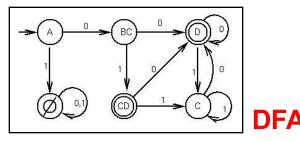
### NFA → DFA Practice



#### Analyzing the Reduction

- Can reduce any NFA to a DFA using subset alg.
- How many states in the DFA?
  - Each DFA state is a subset of the set of NFA states.
  - Given NFA with n states, DFA may have 2<sup>n</sup> states
    - > Since a set with n items may have 2<sup>n</sup> subsets
  - Corollary
    - Reducing a NFA with n states may be O(2<sup>n</sup>)

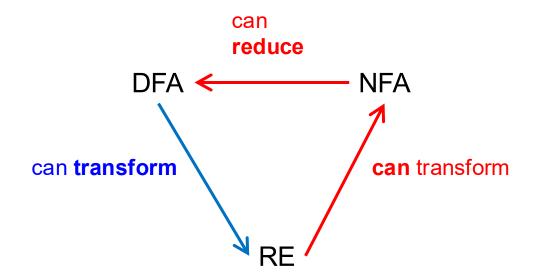




#### Recap: Matching a Regexp R

- ▶ Given R, construct NFA. Takes time O(R)
- ▶ Convert NFA to DFA. Takes time  $O(2^{|R|})$ 
  - But usually not the worst case in practice
- Use DFA to accept/reject string s
  - Assume we can compute  $\delta(q,\sigma)$  in constant time
  - Then time to process s is O(|s|)
    - Can't get much faster!
- Constructing the DFA is a one-time cost
  - But then processing strings is fast

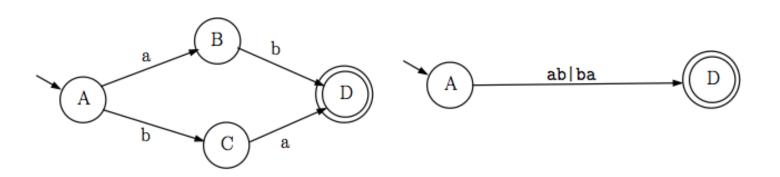
### Closing the Loop: Reducing DFA to RE



#### Reducing DFAs to REs

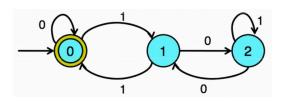
#### General idea

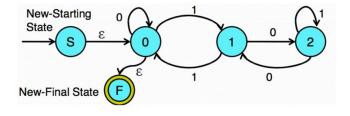
- Remove states one by one, labeling transitions with regular expressions
- When two states are left (start and final), the transition label is the regular expression for the DFA

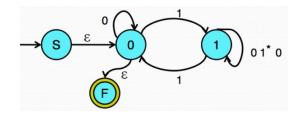


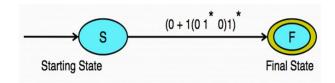
#### DFA to RE example

Language over  $\Sigma = \{0,1\}$  such that every string is a multiple of 3 in binary





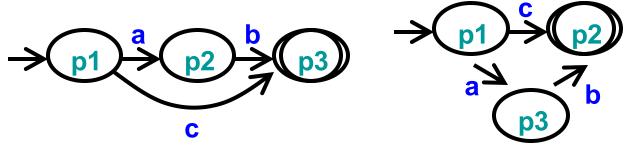




#### Minimizing DFAs

- Every regular language is recognizable by a unique minimum-state DFA
  - Ignoring the particular names of states
- In other words
  - For every DFA, there is a unique DFA with minimum number of states that accepts the same language

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#### Minimizing DFA: Hopcroft Reduction

#### Intuition

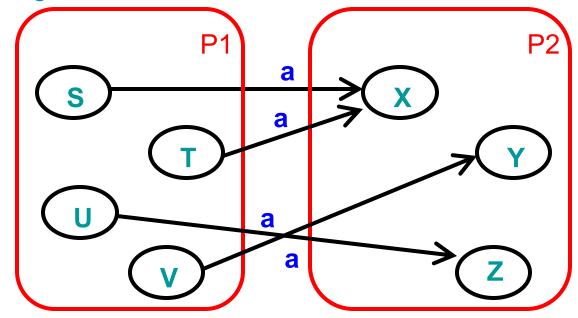
- Look to distinguish states from each other
  - > End up in different accept / non-accept state with identical input

#### Algorithm

- Construct initial partition
  - Accepting & non-accepting states
- Iteratively split partitions (until partitions remain fixed)
  - Split a partition if members in partition have transitions to different partitions for same input
    - Two states x, y belong in same partition if and only if for all symbols in  $\Sigma$  they transition to the same partition
- Update transitions & remove dead states

#### **Splitting Partitions**

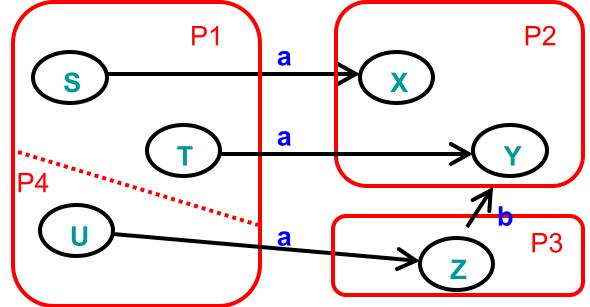
- No need to split partition {S,T,U,V}
  - All transitions on a lead to identical partition P2
  - Even though transitions on a lead to different states



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#### Splitting Partitions (cont.)

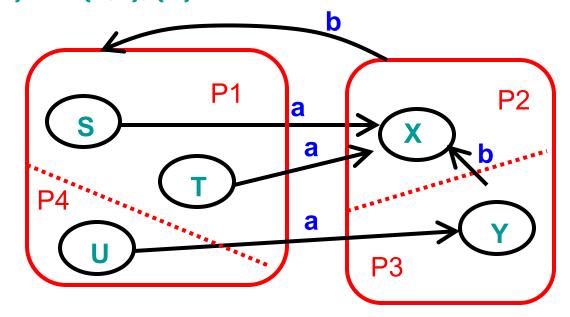
- Need to split partition {S,T,U} into {S,T}, {U}
  - Transitions on a from S,T lead to partition P2
  - Transition on a from U lead to partition P3



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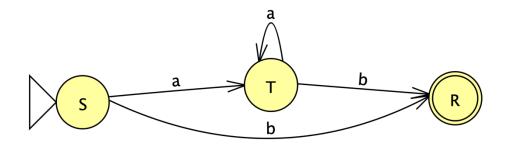
#### Resplitting Partitions

- Need to reexamine partitions after splits
  - Initially no need to split partition {S,T,U}
  - After splitting partition {X,Y} into {X}, {Y} we need to split partition {S,T,U} into {S,T}, {U}



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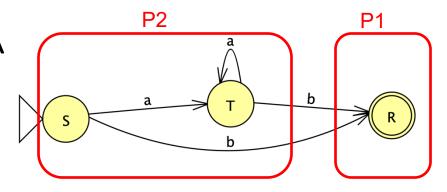
DFA

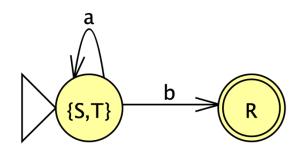


Initial partitions

Split partition

DFA





- Initial partitions
  - Accept

$$\{R\} = P1$$

Reject

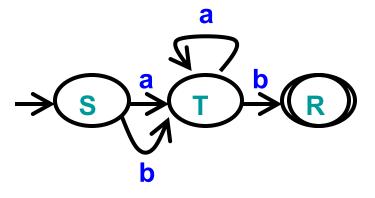
$$\{S,T\}=P2$$

Split partition?

- → Not required, minimization done
- $move(S,a) = T \in P2$

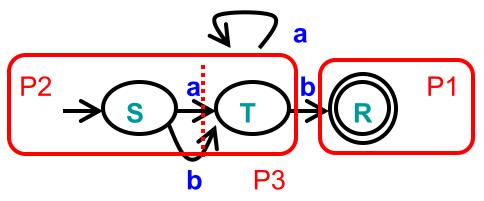
$$- \text{move}(S,b) = R \in P1$$

- $move(T,a) = T \in P2$   $move(T,b) = R \in P1$



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DFA



- Initial partitions
  - Accept { R }= P1
  - Reject { S, T } = P2
- ▶ Split partition? → Yes, different partitions for B
  - $move(S,a) = T \in P2$   $move(S,b) = T \in P2$
  - $move(T,a) = T \in P2$   $-move(T,b) = R \in P1$

DFA

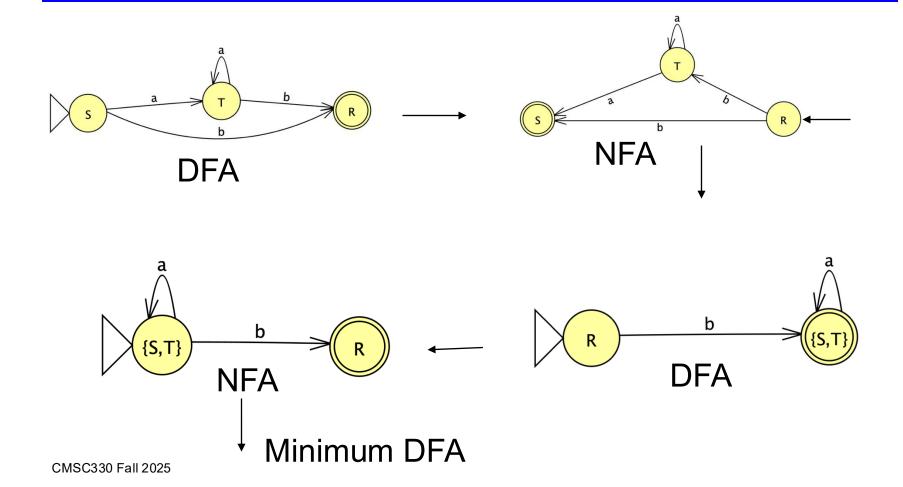
already

minimal

#### Brzozowski's algorithm

- Given a DFA, reverse all the edges, make the initial state an accept state, and the accept states initial, to get an NFA
- 2. NFA-> DFA
- 3. For the new DFA, reverse the edges (and initial-accept swap) get an NFA
- 4. NFA -> DFA

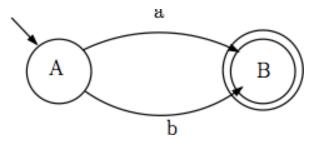
#### Brzozowski's algorithm



#### Complement of DFA

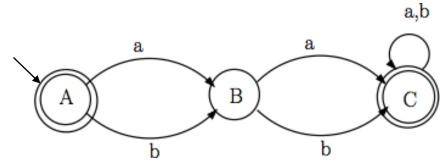
- Given a DFA accepting language L
  - How can we create a DFA accepting its complement?
  - Example DFA

$$> \Sigma = \{a,b\}$$



#### Complement of DFA

- Algorithm
  - Add explicit transitions to a dead state
  - Change every accepting state to a non-accepting state & every non-accepting state to an accepting state
- Note this only works with DFAs
  - Why not with NFAs?



## Summary of Regular Expression Theory

- Finite automata
  - DFA, NFA
- Equivalence of RE, NFA, DFA
  - RE → NFA
    - > Concatenation, union, closure
  - NFA → DFA
    - > ε-closure & subset algorithm
- DFA
  - Minimization, complementation