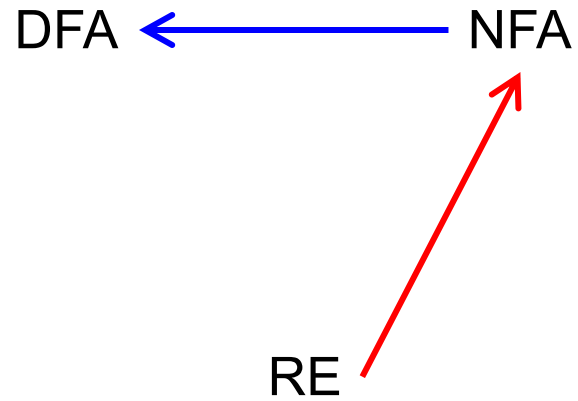


CMSC 330: Organization of Programming Languages

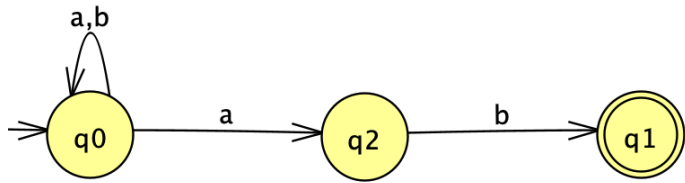
Reducing NFA to DFA and DFAs Minimization

Reducing NFA to DFA

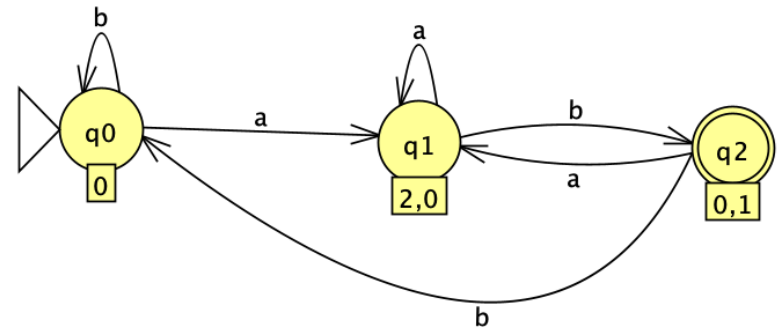


Why NFA \rightarrow DFA

- ▶ DFA is generally more efficient than NFA



NFA



DFA

Language: $(a|b)^*ab$

How to accept **bab**?

Why NFA \rightarrow DFA

- ▶ DFA has the same expressive power as NFAs.
 - Let language $L \subseteq \Sigma^*$, and suppose L is accepted by NFA $N = (\Sigma, Q, q_0, F, \delta)$. There exists a DFA $D = (\Sigma, Q', q'_0, F', \delta')$ that also accepts L . ($L(N) = L(D)$)
- ▶ NFAs are more flexible and easier to build. But it is not more powerful than DFAs

NFA \leftrightarrow DFA

How to Convert NFA to DFA

Subset Construction Algorithm

Input NFA $(\Sigma, Q, q_0, F_n, \delta)$

Output DFA $(\Sigma, R, r_0, F_d, \delta')$

Subset Construction Algorithm

Input NFA $(\Sigma, Q, q_0, F_n, \delta)$ Output DFA $(\Sigma, R, r_0, F_d, \delta')$

Let $r_0 = \varepsilon\text{-closure}(\delta, q_0)$, add it to R

While \exists an unmarked state $r \in R$

 Mark r

 For each $\sigma \in \Sigma$

 Let $E = \text{move}(\delta, r, \sigma)$

 Let $e = \varepsilon\text{-closure}(\delta, E)$

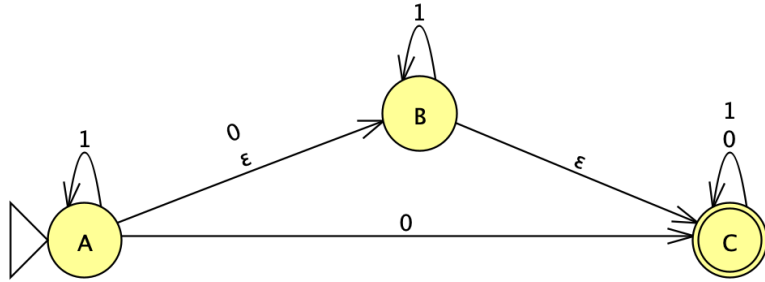
 If $e \notin R$

 Let $R = R \cup \{e\}$

 Let $\delta' = \delta' \cup \{r, \sigma, e\}$

Let $F_d = \{r \mid \exists s \in r \text{ with } s \in F_n\}$

NFA



→ Let $r_0 = \varepsilon\text{-closure}(\delta, q_0)$, add it to R

While \exists an unmarked state $r \in R$

Mark r

For each $\sigma \in \Sigma$

Let $E = \text{move}(\delta, r, \sigma)$

Let $e = \varepsilon\text{-closure}(\delta, E)$

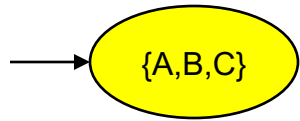
If $e \notin R$

Let $R = R \cup \{e\}$

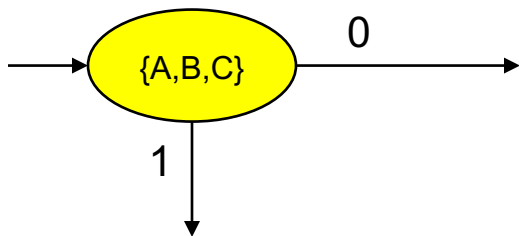
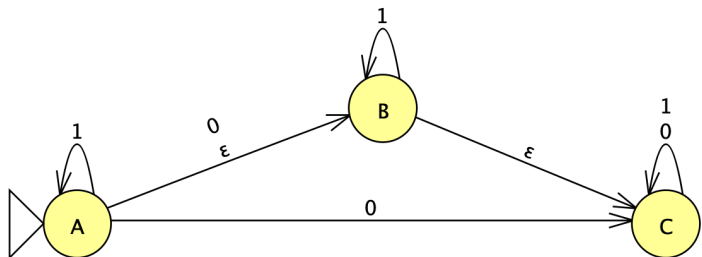
Let $\delta' = \delta' \cup \{r, \sigma, e\}$

Let $F_d = \{r \mid \exists s \in r \text{ with } s \in F_n\}$

DFA



New Start State



Let $r_0 = \varepsilon\text{-closure}(\delta, q_0)$, add it to R

While \exists an unmarked state $r \in R$

Mark r

→ For each $\sigma \in \Sigma$ //0

Let $E = \text{move}(\delta, r, \sigma)$

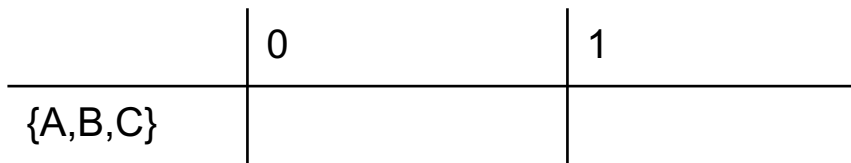
Let $e = \varepsilon\text{-closure}(\delta, E)$

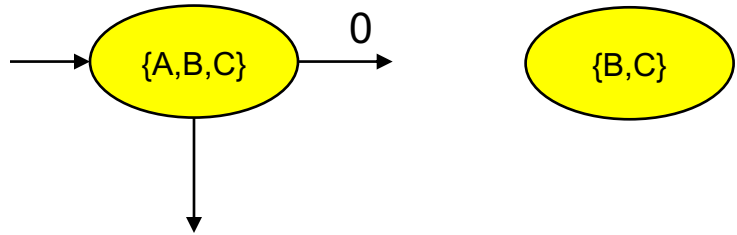
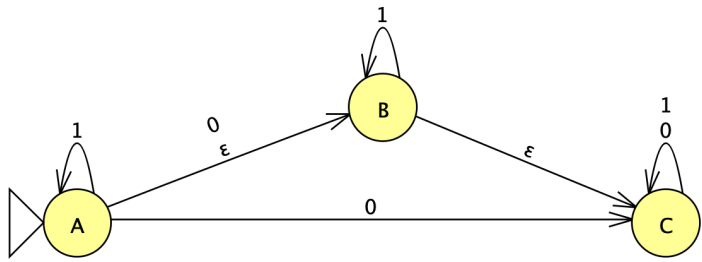
If $e \notin R$

Let $R = R \cup \{e\}$

Let $\delta' = \delta' \cup \{r, \sigma, e\}$

Let $F_d = \{r \mid \exists s \in r \text{ with } s \in F_n\}$





	0	1
{A,B,C}	{B,C}	

Let $r_0 = \varepsilon\text{-closure}(\delta, q_0)$, add it to R

While \exists an unmarked state $r \in R$

Mark r

For each $\sigma \in \Sigma$

Let $E = \text{move}(\delta, r, \sigma)$

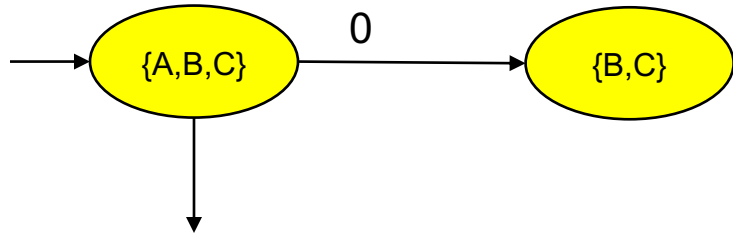
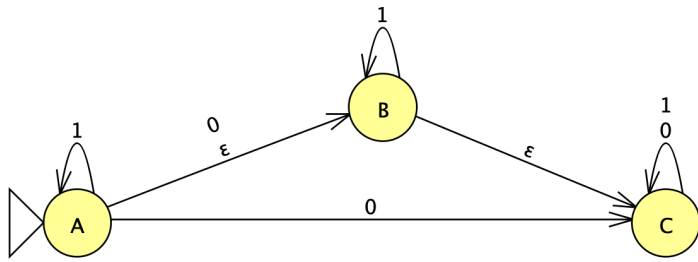
→ Let $e = \varepsilon\text{-closure}(\delta, E)$

If $e \notin R$

Let $R = R \cup \{e\}$

Let $\delta' = \delta' \cup \{r, \sigma, e\}$

Let $F_d = \{r \mid \exists s \in r \text{ with } s \in F_n\}$



Let $r_0 = \varepsilon\text{-closure}(\delta, q_0)$, add it to R

While \exists an unmarked state $r \in R$

Mark r

For each $\sigma \in \Sigma$

Let $E = \text{move}(\delta, r, \sigma)$

Let $e = \varepsilon\text{-closure}(\delta, E)$

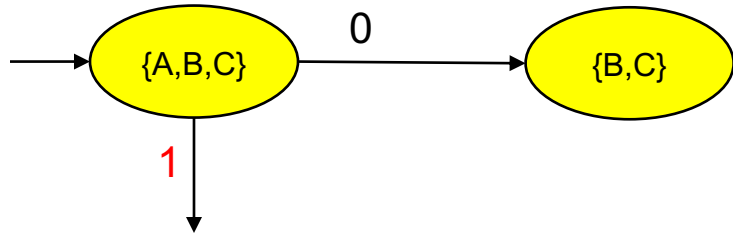
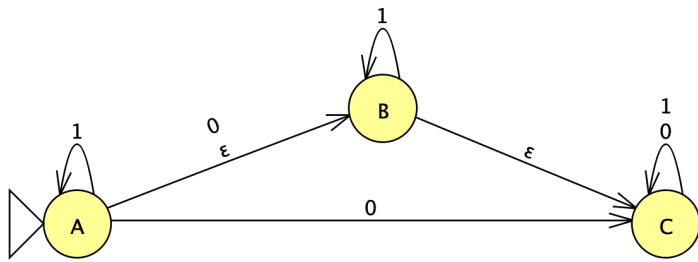
If $e \notin R$

Let $R = R \cup \{e\}$

→ Let $\delta' = \delta' \cup \{r, \sigma, e\}$

Let $F_d = \{r \mid \exists s \in r \text{ with } s \in F_n\}$

	0	1
{A,B,C}	{B,C}	
{B,C}		



Let $r_0 = \varepsilon\text{-closure}(\delta, q_0)$, add it to R

While \exists an unmarked state $r \in R$

Mark r

→ For each $\sigma \in \Sigma$ //1

Let $E = \text{move}(\delta, r, \sigma)$

Let $e = \varepsilon\text{-closure}(\delta, E)$

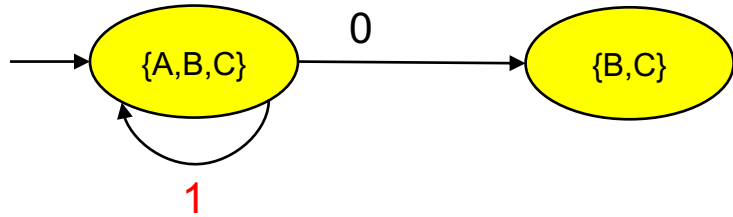
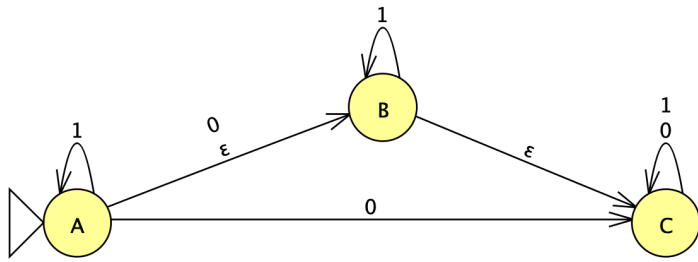
If $e \notin R$

Let $R = R \cup \{e\}$

Let $\delta' = \delta' \cup \{r, \sigma, e\}$

Let $F_d = \{r \mid \exists s \in r \text{ with } s \in F_n\}$

	0	1
{A,B,C}	{B,C}	
{B,C}		



Let $r_0 = \varepsilon\text{-closure}(\delta, q_0)$, add it to R

While \exists an unmarked state $r \in R$

Mark r

For each $\sigma \in \Sigma$ //1

Let $E = \text{move}(\delta, r, \sigma)$

→ Let $e = \varepsilon\text{-closure}(\delta, E)$

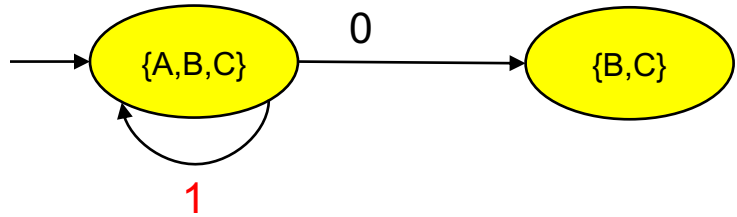
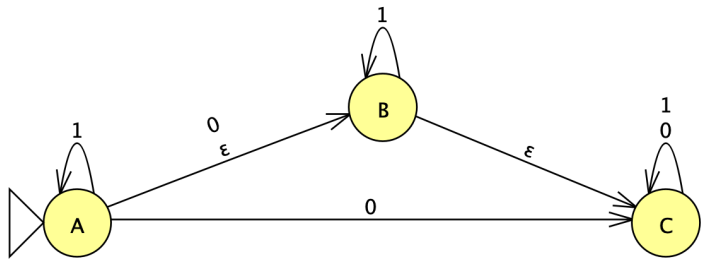
If $e \notin R$

Let $R = R \cup \{e\}$

Let $\delta' = \delta' \cup \{r, \sigma, e\}$

Let $F_d = \{r \mid \exists s \in r \text{ with } s \in F_n\}$

	0	1
{A,B,C}	{B,C}	{A,B,C}
{B,C}		



Let $r_0 = \varepsilon\text{-closure}(\delta, q_0)$, add it to R

While \exists an unmarked state $r \in R$

Mark r

For each $\sigma \in \Sigma$ //1

Let $E = \text{move}(\delta, r, \sigma)$

Let $e = \varepsilon\text{-closure}(\delta, E)$

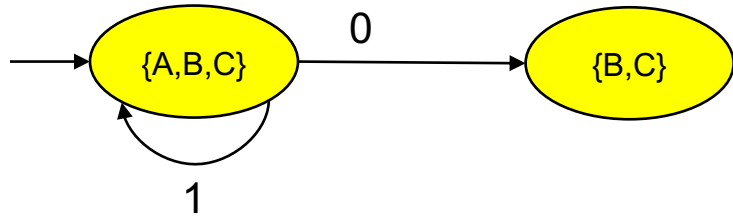
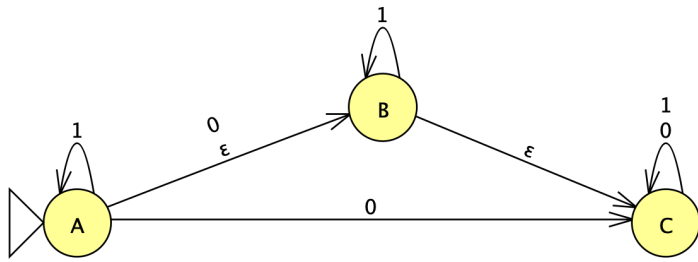
If $e \notin R$

Let $R = R \cup \{e\}$

→ Let $\delta' = \delta' \cup \{r, \sigma, e\}$

Let $F_d = \{r \mid \exists s \in r \text{ with } s \in F_n\}$

	0	1
{A,B,C}	{B,C}	{A,B,C}
{B,C}		



	0	1
{A,B,C}	{B,C}	{A,B,C}
{B,C}		

Let $r_0 = \varepsilon\text{-closure}(\delta, q_0)$, add it to R

→ While \exists an unmarked state $r \in R$

Mark r

For each $\sigma \in \Sigma$ //1

Let $E = \text{move}(\delta, r, \sigma)$

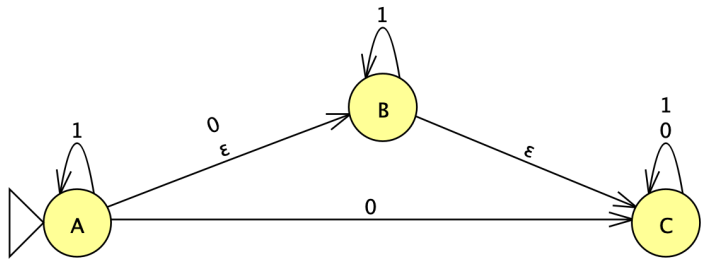
Let $e = \varepsilon\text{-closure}(\delta, E)$

If $e \notin R$

Let $R = R \cup \{e\}$

Let $\delta' = \delta' \cup \{r, \sigma, e\}$

Let $F_d = \{r \mid \exists s \in r \text{ with } s \in F_n\}$



Let $r_0 = \varepsilon\text{-closure}(\delta, q_0)$, add it to R

While \exists an unmarked state $r \in R$

Mark r

→ For each $\sigma \in \Sigma$ //0

Let $E = \text{move}(\delta, r, \sigma)$

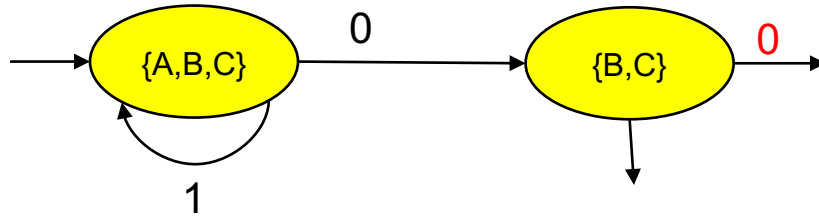
Let $e = \varepsilon\text{-closure}(\delta, E)$

If $e \notin R$

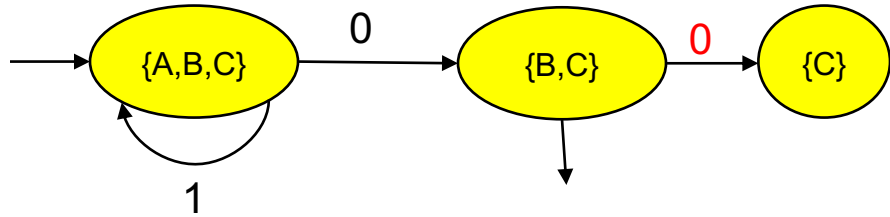
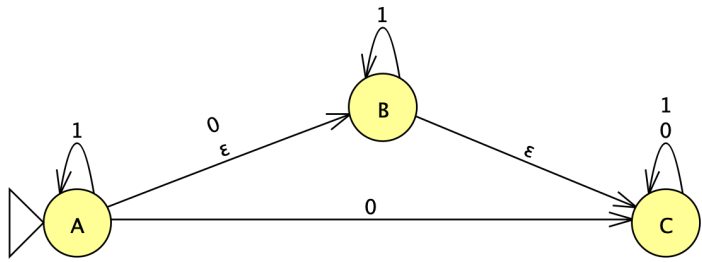
Let $R = R \cup \{e\}$

Let $\delta' = \delta' \cup \{r, \sigma, e\}$

Let $F_d = \{r \mid \exists s \in r \text{ with } s \in F_n\}$



	0	1
{A,B,C}	{B,C}	{A,B,C}
{B,C}		



Let $r_0 = \varepsilon\text{-closure}(\delta, q_0)$, add it to R

While \exists an unmarked state $r \in R$

Mark r

For each $\sigma \in \Sigma$ //0

Let $E = \text{move}(\delta, r, \sigma)$

→ Let $e = \varepsilon\text{-closure}(\delta, E)$

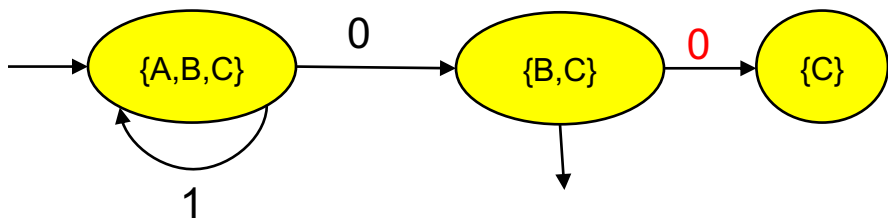
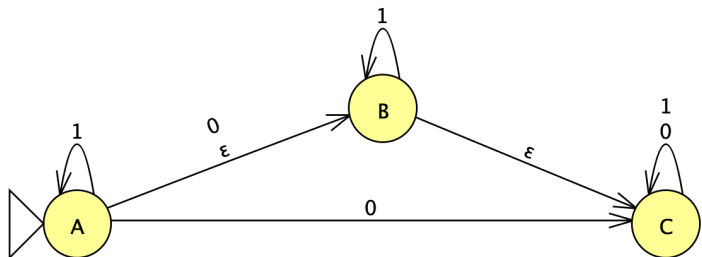
If $e \notin R$

Let $R = R \cup \{e\}$

Let $\delta' = \delta' \cup \{r, \sigma, e\}$

Let $F_d = \{r \mid \exists s \in r \text{ with } s \in F_n\}$

	0	1
{A,B,C}	{B,C}	{A,B,C}
{B,C}	{C}	



	0	1
{A,B,C}	{B,C}	{A,B,C}
{B,C}	{C}	
{C}		

Let $r_0 = \varepsilon\text{-closure}(\delta, q_0)$, add it to R

While \exists an unmarked state $r \in R$

Mark r

For each $\sigma \in \Sigma$ //0

Let $E = \text{move}(\delta, r, \sigma)$

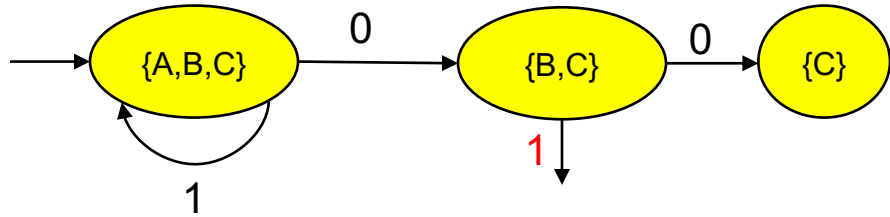
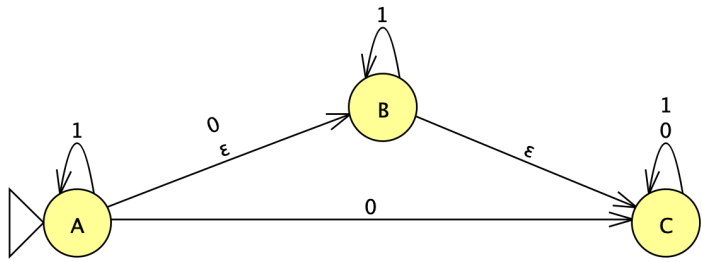
Let $e = \varepsilon\text{-closure}(\delta, E)$

If $e \notin R$

Let $R = R \cup \{e\}$

→ Let $\delta' = \delta' \cup \{r, \sigma, e\}$

Let $F_d = \{r \mid \exists s \in r \text{ with } s \in F_n\}$



Let $r_0 = \varepsilon\text{-closure}(\delta, q_0)$, add it to R

While \exists an unmarked state $r \in R$

Mark r

→ For each $\sigma \in \Sigma$ //1

Let $E = \text{move}(\delta, r, \sigma)$

Let $e = \varepsilon\text{-closure}(\delta, E)$

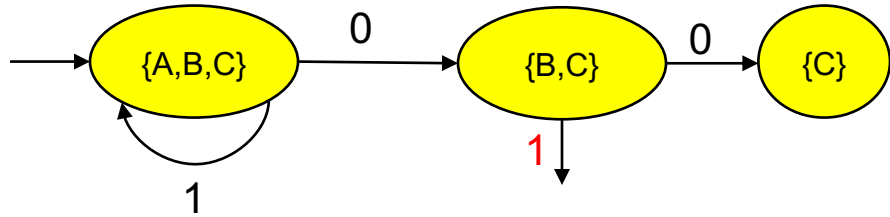
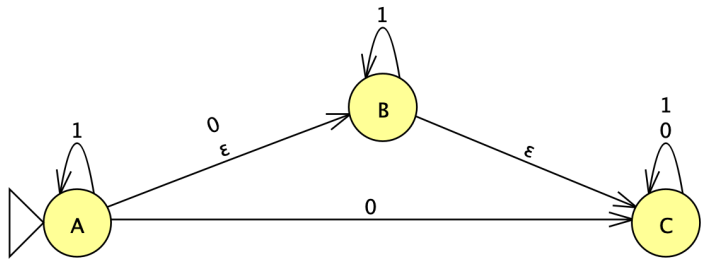
If $e \notin R$

Let $R = R \cup \{e\}$

Let $\delta' = \delta' \cup \{r, \sigma, e\}$

Let $F_d = \{r \mid \exists s \in r \text{ with } s \in F_n\}$

	0	1
{A,B,C}	{B,C}	{A,B,C}
{B,C}	{C}	?
{C}		



Let $r_0 = \varepsilon\text{-closure}(\delta, q_0)$, add it to R

While \exists an unmarked state $r \in R$

Mark r

For each $\sigma \in \Sigma$ //1

Let $E = \text{move}(\delta, r, \sigma)$

→ Let $e = \varepsilon\text{-closure}(\delta, E)$

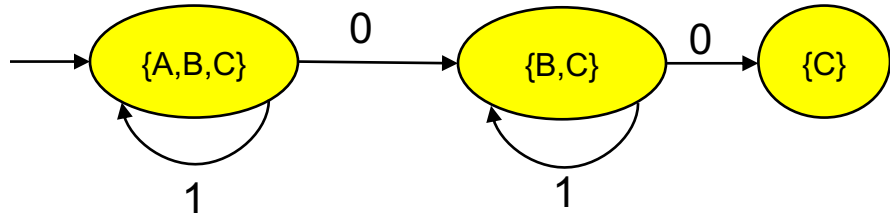
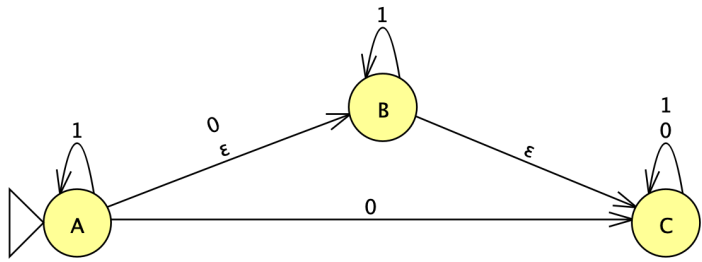
If $e \notin R$

Let $R = R \cup \{e\}$

Let $\delta' = \delta' \cup \{r, \sigma, e\}$

Let $F_d = \{r \mid \exists s \in r \text{ with } s \in F_n\}$

	0	1
{A,B,C}	{B,C}	{A,B,C}
{B,C}	{C}	{B,C}
{C}		



Let $r_0 = \varepsilon\text{-closure}(\delta, q_0)$, add it to R

While \exists an unmarked state $r \in R$

Mark r

For each $\sigma \in \Sigma$ //1

Let $E = \text{move}(\delta, r, \sigma)$

Let $e = \varepsilon\text{-closure}(\delta, E)$

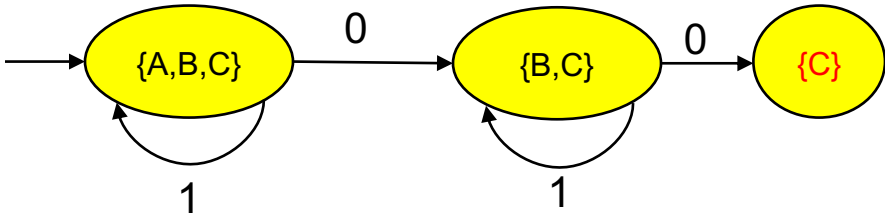
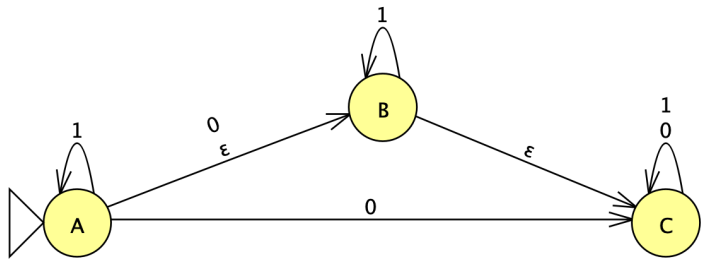
If $e \notin R$

Let $R = R \cup \{e\}$

→ Let $\delta' = \delta' \cup \{r, \sigma, e\}$

Let $F_d = \{r \mid \exists s \in r \text{ with } s \in F_n\}$

	0	1
{A,B,C}	{B,C}	{A,B,C}
{B,C}	{C}	{B,C}
{C}		



Let $r_0 = \varepsilon\text{-closure}(\delta, q_0)$, add it to R

→ While \exists an unmarked state $r \in R$

Mark r

For each $\sigma \in \Sigma$ //1

Let $E = \text{move}(\delta, r, \sigma)$

Let $e = \varepsilon\text{-closure}(\delta, E)$

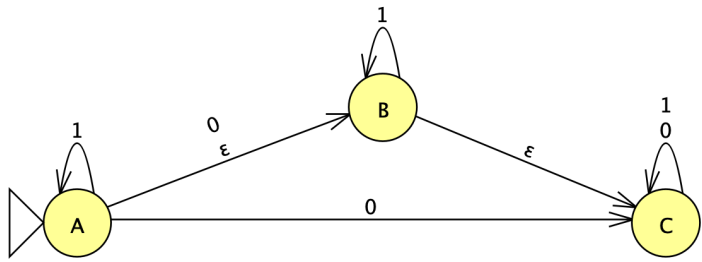
If $e \notin R$

Let $R = R \cup \{e\}$

Let $\delta' = \delta' \cup \{r, \sigma, e\}$

Let $F_d = \{r \mid \exists s \in r \text{ with } s \in F_n\}$

	0	1
{A,B,C}	{B,C}	{A,B,C}
{B,C}	{C}	{B,C}
{C}		



Let $r_0 = \varepsilon\text{-closure}(\delta, q_0)$, add it to R

While \exists an unmarked state $r \in R$

Mark r

→ For each $\sigma \in \Sigma$

Let $E = \text{move}(\delta, r, \sigma)$

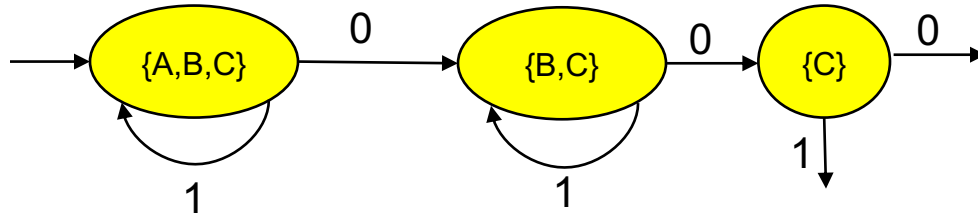
Let $e = \varepsilon\text{-closure}(\delta, E)$

If $e \notin R$

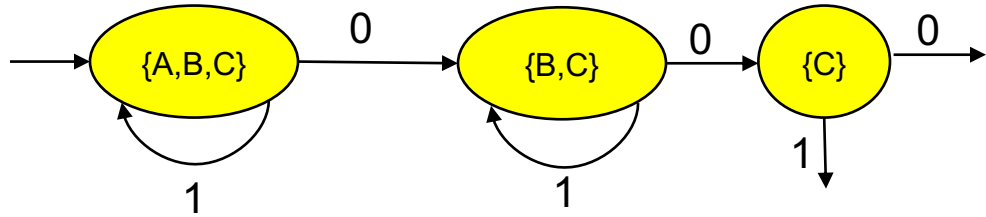
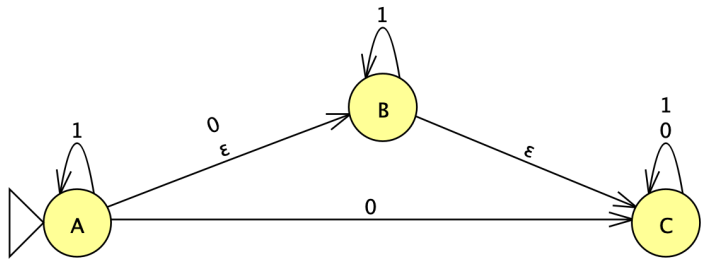
Let $R = R \cup \{e\}$

Let $\delta' = \delta' \cup \{r, \sigma, e\}$

Let $F_d = \{r \mid \exists s \in r \text{ with } s \in F_n\}$



	0	1
{A,B,C}	{B,C}	{A,B,C}
{B,C}	{C}	{B,C}
{C}		



Let $r_0 = \varepsilon\text{-closure}(\delta, q_0)$, add it to R

While \exists an unmarked state $r \in R$

Mark r

For each $\sigma \in \Sigma$ //0

Let $E = \text{move}(\delta, r, \sigma)$

→ Let $e = \varepsilon\text{-closure}(\delta, E)$

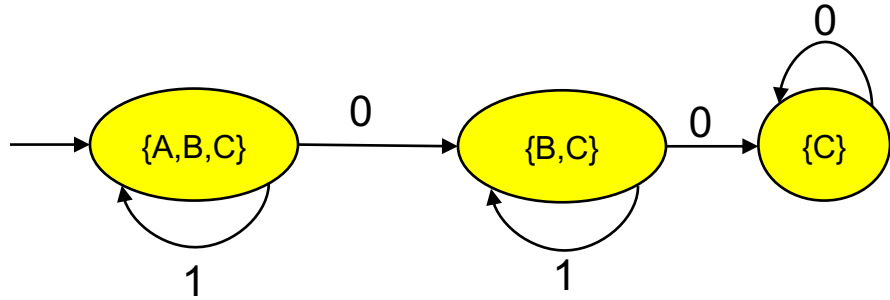
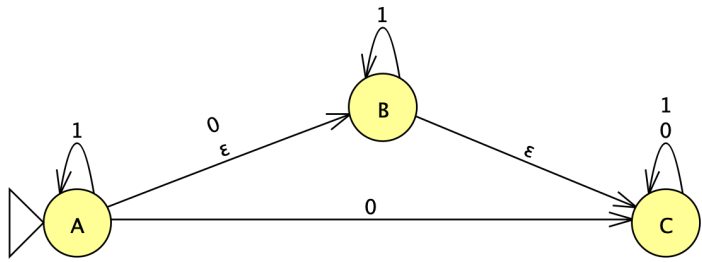
If $e \notin R$

Let $R = R \cup \{e\}$

Let $\delta' = \delta' \cup \{r, \sigma, e\}$

Let $F_d = \{r \mid \exists s \in r \text{ with } s \in F_n\}$

	0	1
{A,B,C}	{B,C}	{A,B,C}
{B,C}	{C}	{B,C}
{C}	{C}	



Let $r_0 = \varepsilon\text{-closure}(\delta, q_0)$, add it to R

While \exists an unmarked state $r \in R$

Mark r

For each $\sigma \in \Sigma$ //0

Let $E = \text{move}(\delta, r, \sigma)$

Let $e = \varepsilon\text{-closure}(\delta, E)$

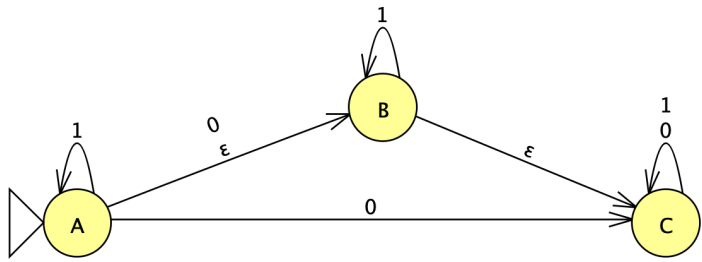
If $e \notin R$

Let $R = R \cup \{e\}$

→ Let $\delta' = \delta' \cup \{r, \sigma, e\}$

Let $F_d = \{r \mid \exists s \in r \text{ with } s \in F_n\}$

	0	1
{A,B,C}	{B,C}	{A,B,C}
{B,C}	{C}	{B,C}
{C}	{C}	



Let $r_0 = \varepsilon\text{-closure}(\delta, q_0)$, add it to R

While \exists an unmarked state $r \in R$

Mark r

→ For each $\sigma \in \Sigma$ //1

Let $E = \text{move}(\delta, r, \sigma)$

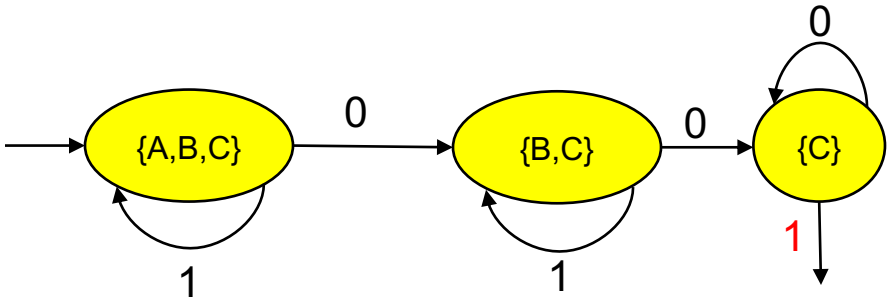
Let $e = \varepsilon\text{-closure}(\delta, E)$

If $e \notin R$

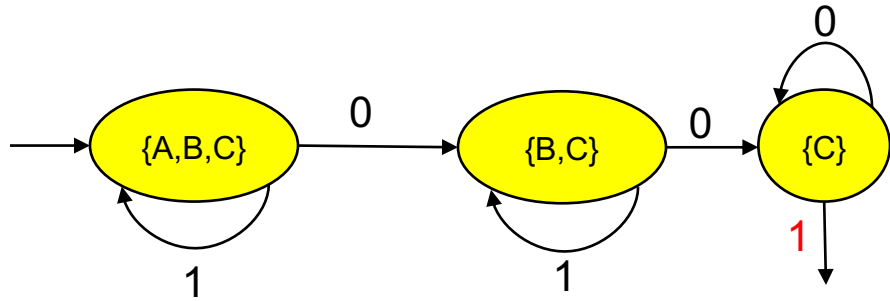
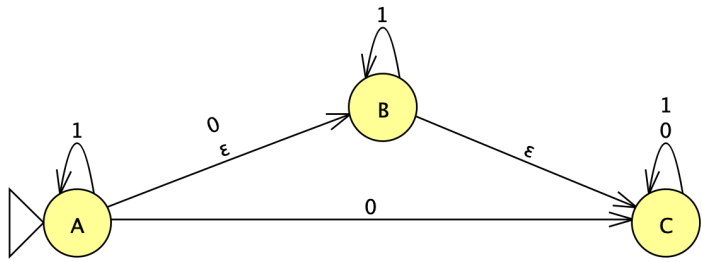
Let $R = R \cup \{e\}$

Let $\delta' = \delta' \cup \{r, \sigma, e\}$

Let $F_d = \{r \mid \exists s \in r \text{ with } s \in F_n\}$



	0	1
{A,B,C}	{B,C}	{A,B,C}
{B,C}	{C}	{B,C}
{C}	{C}	



Let $r_0 = \varepsilon\text{-closure}(\delta, q_0)$, add it to R

While \exists an unmarked state $r \in R$

Mark r

For each $\sigma \in \Sigma$ //1

Let $E = \text{move}(\delta, r, \sigma)$

→ Let $e = \varepsilon\text{-closure}(\delta, E)$

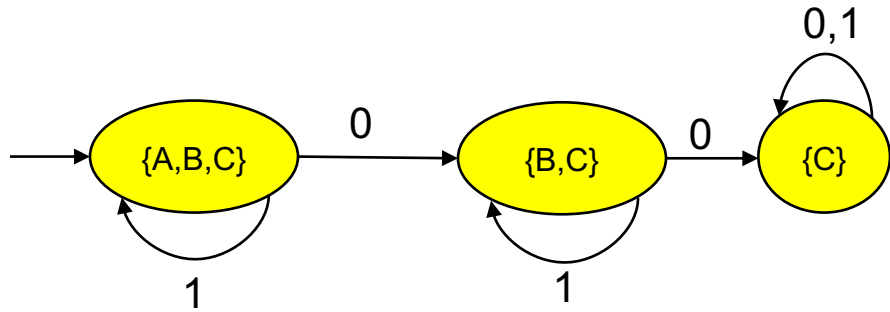
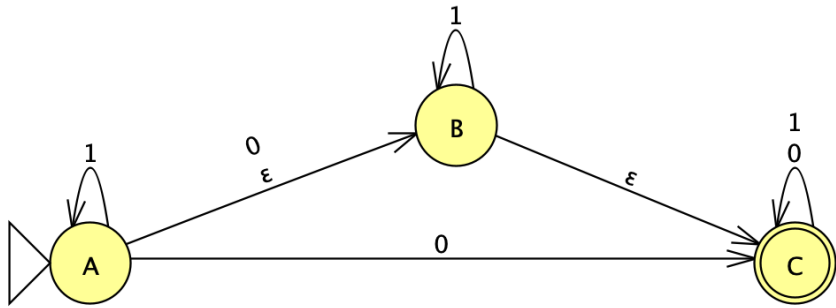
If $e \notin R$

Let $R = R \cup \{e\}$

Let $\delta' = \delta' \cup \{r, \sigma, e\}$

Let $F_d = \{r \mid \exists s \in r \text{ with } s \in F_n\}$

	0	1
{A,B,C}	{B,C}	{A,B,C}
{B,C}	{C}	{B,C}
{C}	{C}	{C}



Let $r_0 = \varepsilon\text{-closure}(\delta, q_0)$, add it to R

While \exists an unmarked state $r \in R$

Mark r

For each $\sigma \in \Sigma$ //1

Let $E = \text{move}(\delta, r, \sigma)$

Let $e = \varepsilon\text{-closure}(\delta, E)$

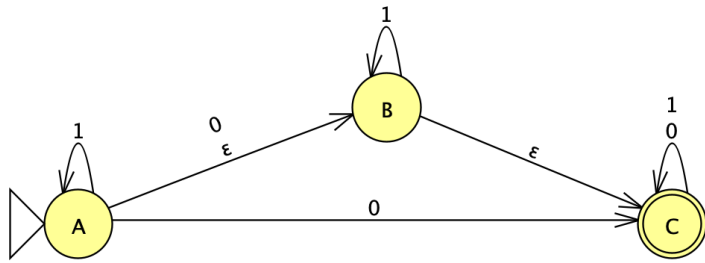
If $e \notin R$

Let $R = R \cup \{e\}$

→ Let $\delta' = \delta' \cup \{r, \sigma, e\}$

Let $F_d = \{r \mid \exists s \in r \text{ with } s \in F_n\}$

	0	1
{A,B,C}	{B,C}	{A,B,C}
{B,C}	{C}	{B,C}
{C}	{C}	{C}



Let $r_0 = \varepsilon\text{-closure}(\delta, q_0)$, add it to R

While \exists an unmarked state $r \in R$

Mark r

For each $\sigma \in \Sigma$ //1

Let $E = \text{move}(\delta, r, \sigma)$

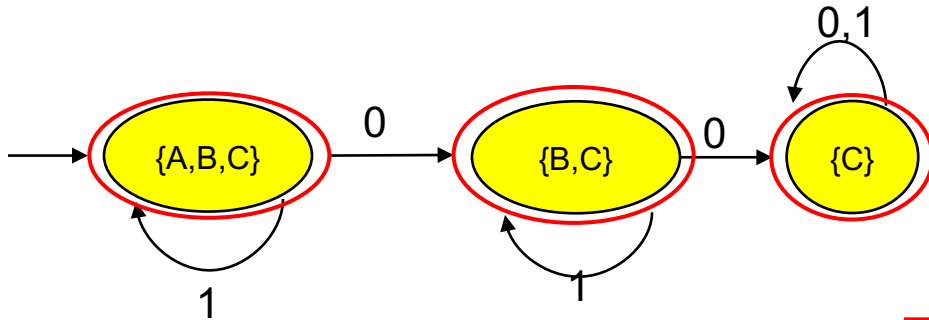
Let $e = \varepsilon\text{-closure}(\delta, E)$

If $e \notin R$

Let $R = R \cup \{e\}$

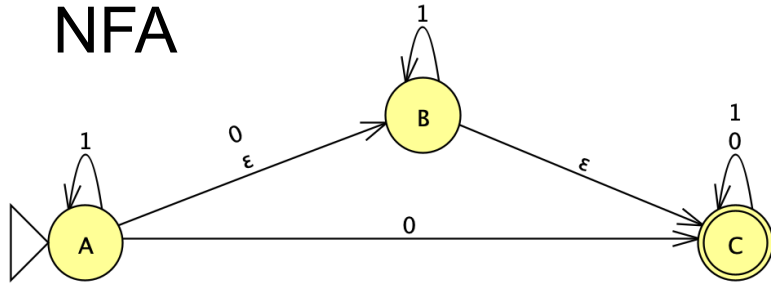
Let $\delta' = \delta' \cup \{r, \sigma, e\}$

→ Let $F_d = \{r \mid \exists s \in r \text{ with } s \in F_n\}$



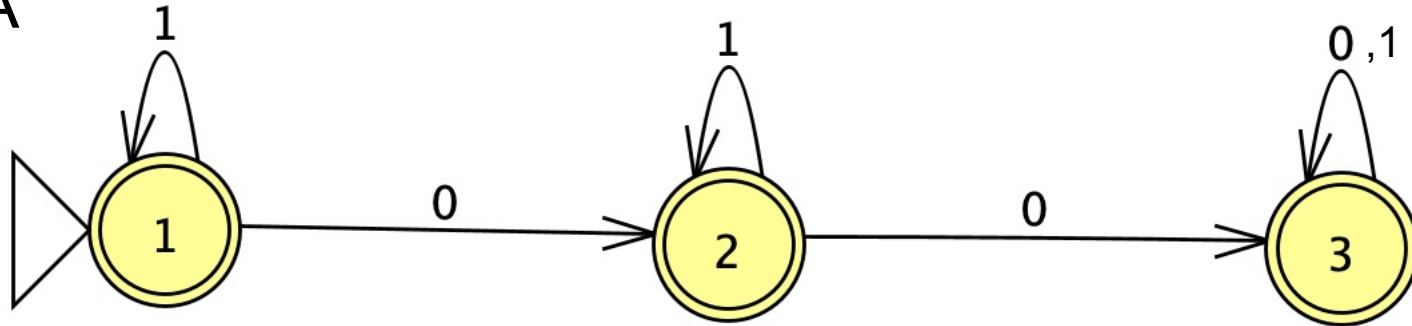
	0	1
{A,B,C}	{B,C}	{A,B,C}
{B,C}	{C}	{B,C}
{C}	{C}	{C}

NFA

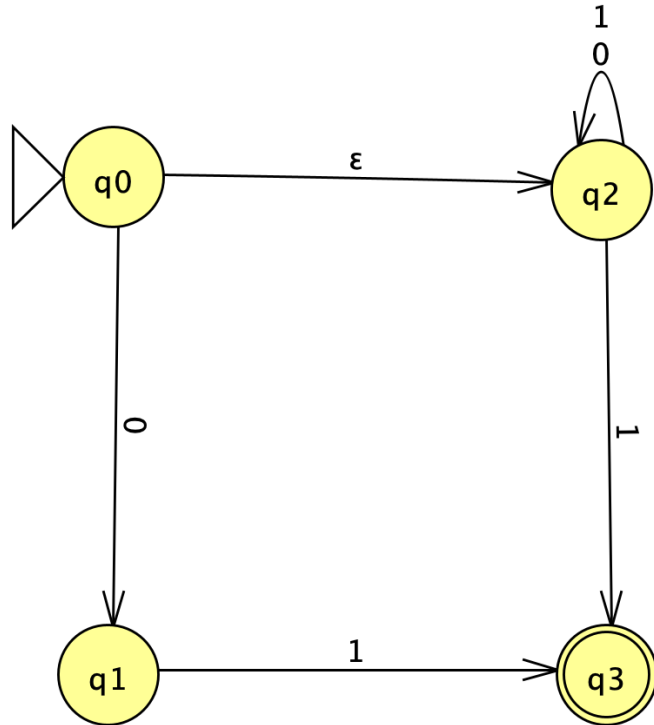


	0	1
{A,B,C}	{B,C}	{A,B,C}
{B,C}	{C}	{B,C}
{C}	{C}	{C}

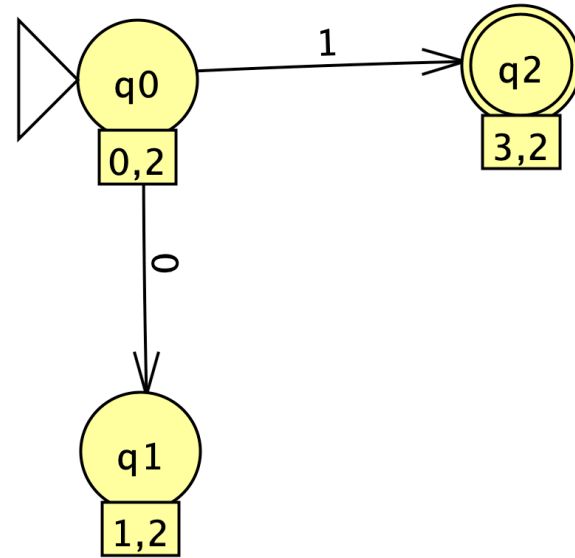
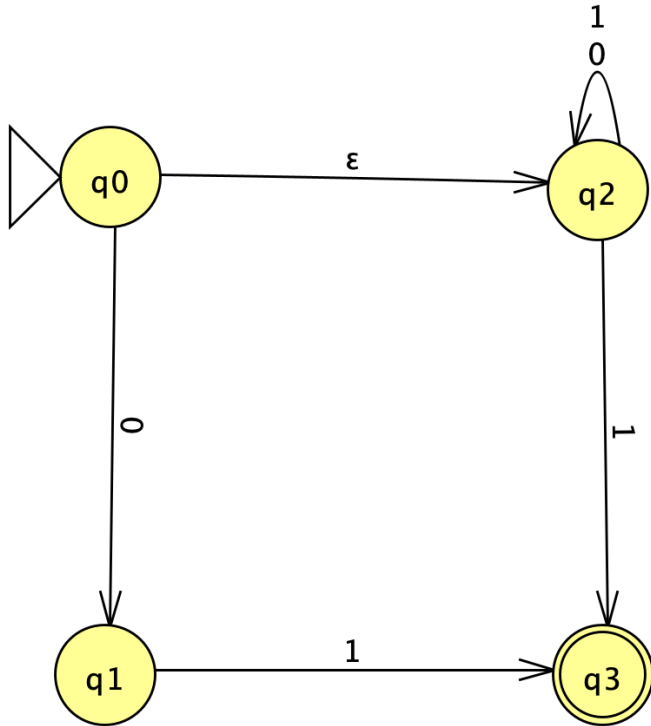
DFA



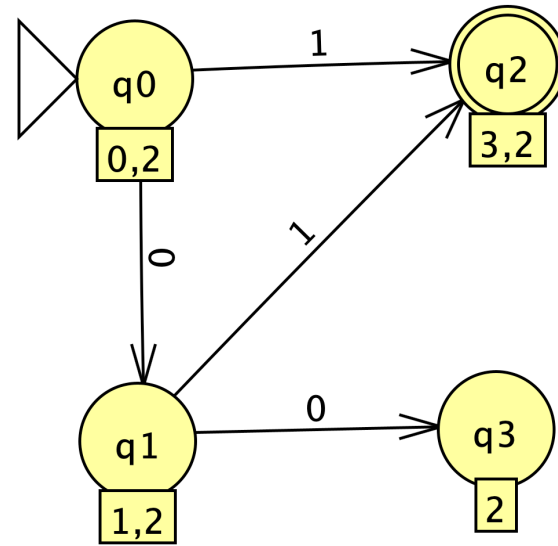
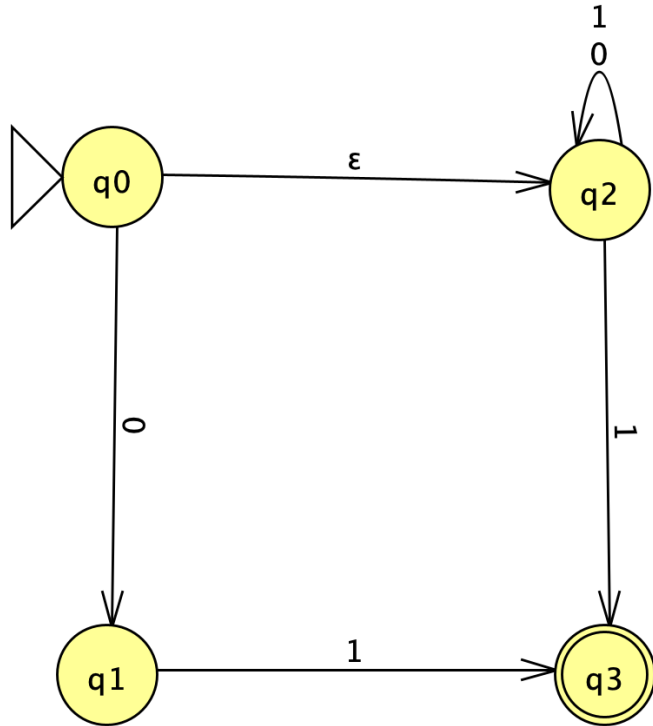
NFA \rightarrow DFA Another Example



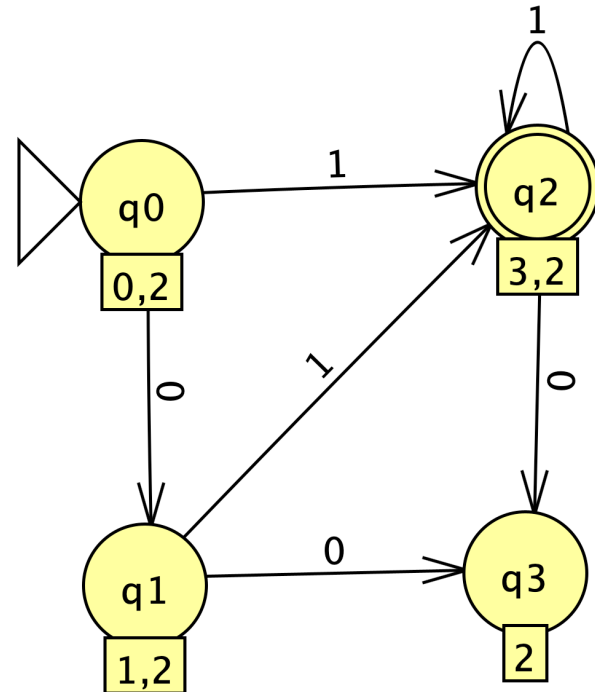
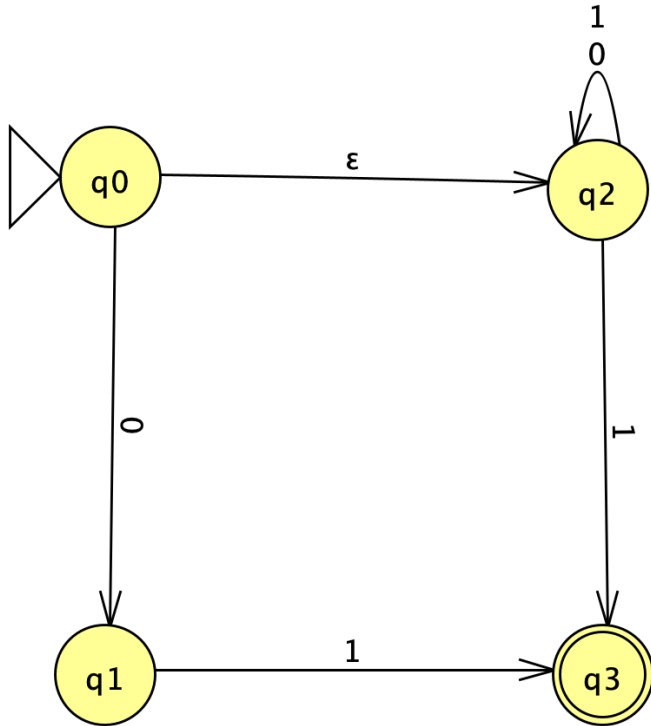
NFA \rightarrow DFA Another Example



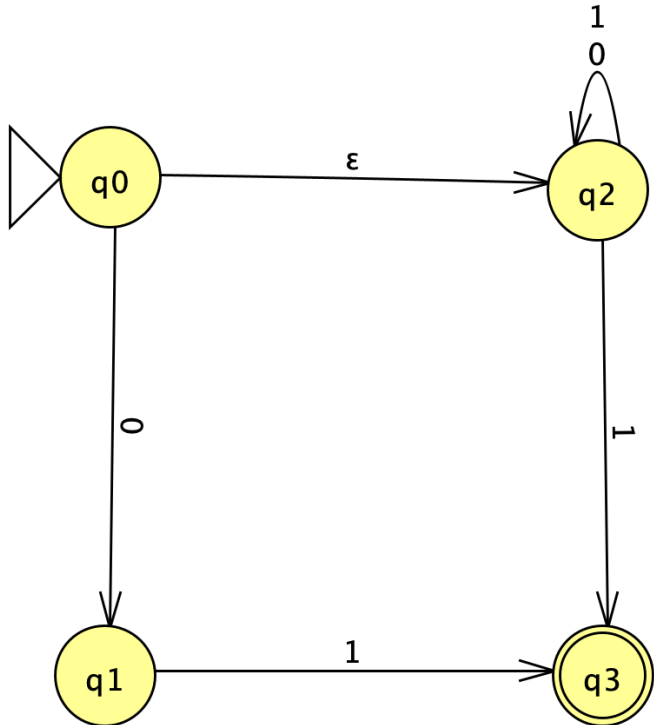
NFA \rightarrow DFA Another Example



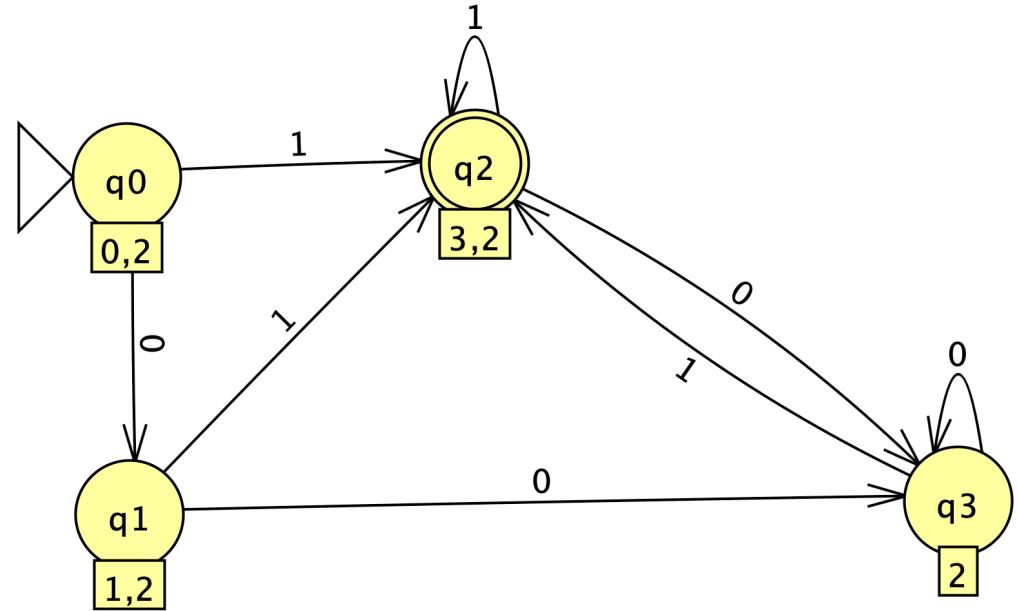
NFA \rightarrow DFA Another Example



NFA \rightarrow DFA Another Example

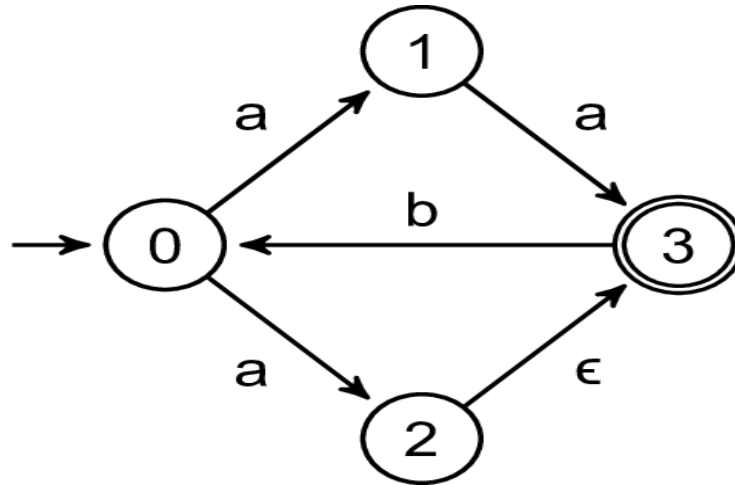


NFA

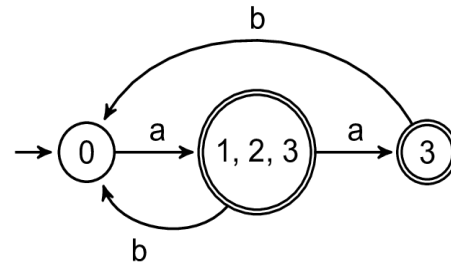
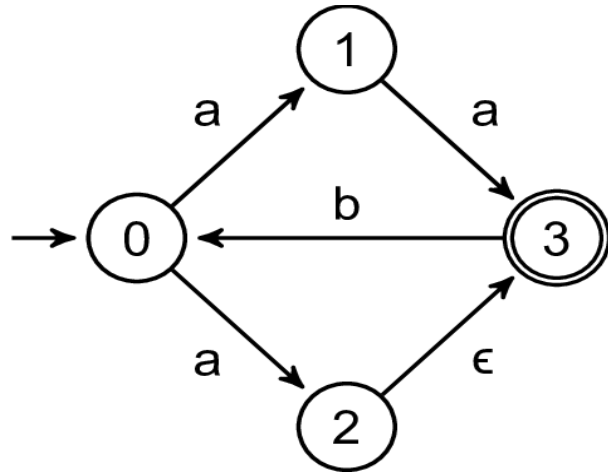


DFA

NFA \rightarrow DFA Practice

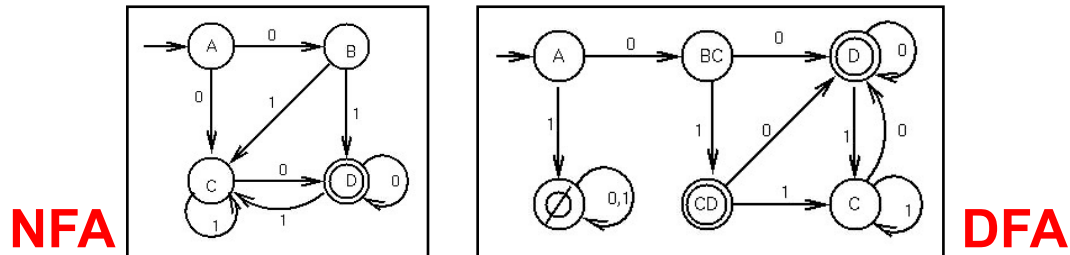


NFA \rightarrow DFA Practice



Analyzing the Reduction

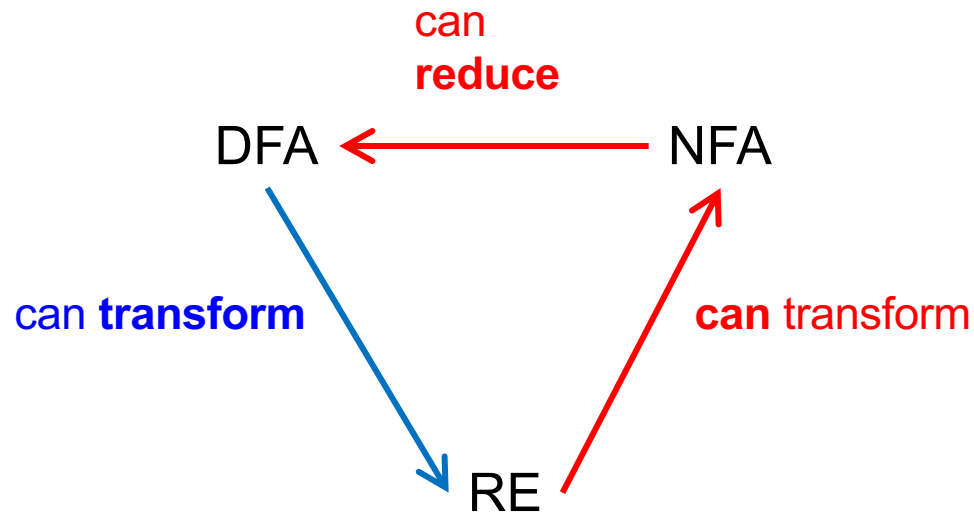
- ▶ Can reduce any NFA to a DFA using subset alg.
- ▶ How many states in the DFA?
 - Each DFA state is a subset of the set of NFA states
 - Given NFA with n states, DFA may have 2^n states
 - Since a set with n items may have 2^n subsets
 - Corollary
 - Reducing a NFA with n states may be $O(2^n)$



Recap: Matching a Regexp R

- ▶ Given R , construct NFA. Takes time $O(R)$
- ▶ Convert NFA to DFA. Takes time $O(2^{|R|})$
 - But usually not the worst case in practice
- ▶ Use DFA to accept/reject string s
 - Assume we can compute $\delta(q, \sigma)$ in constant time
 - Then time to process s is $O(|s|)$
 - Can't get much faster!
- ▶ Constructing the DFA is a one-time cost
 - But then processing strings is fast

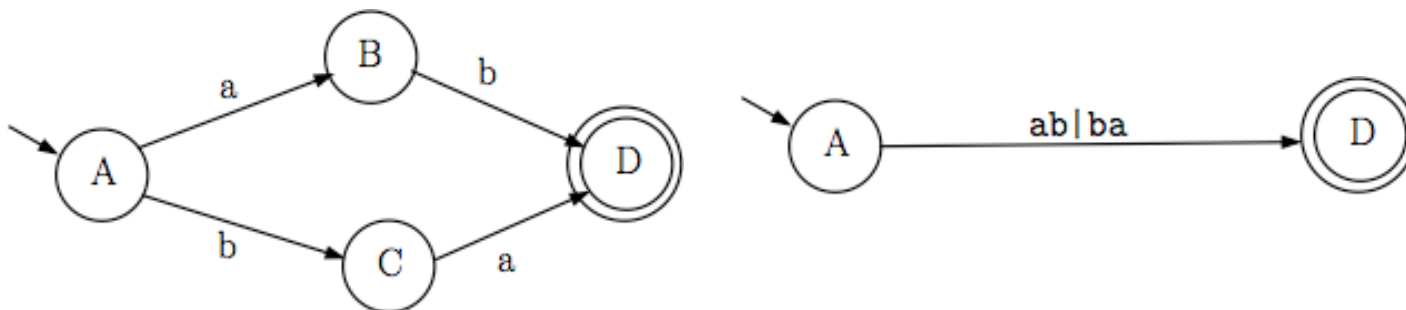
Closing the Loop: Reducing DFA to RE



Reducing DFAs to REs

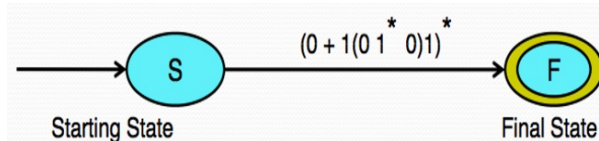
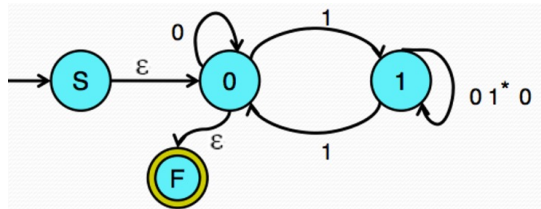
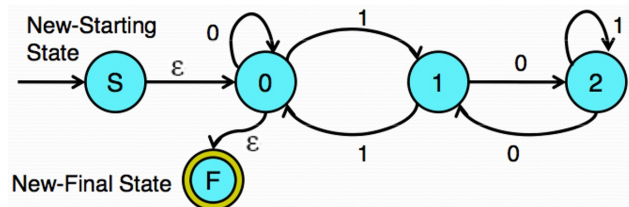
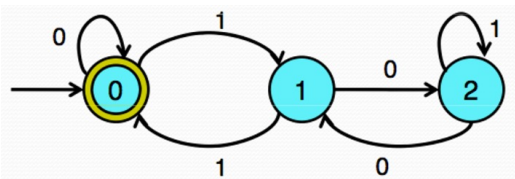
▶ General idea

- Remove states one by one, labeling transitions with regular expressions
- When two states are left (start and final), the transition label is the regular expression for the DFA



DFA to RE example

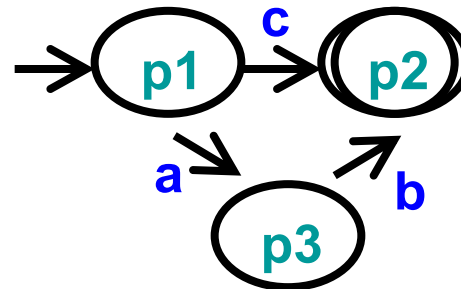
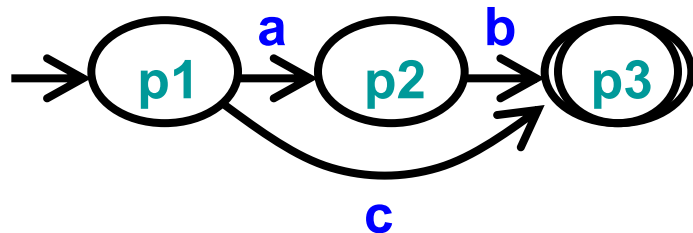
Language over $\Sigma = \{0,1\}$ such that every string is a multiple of 3 in binary



$$(0 + 1(01^*0)1)^*$$

Minimizing DFAs

- ▶ Every regular language is recognizable by a **unique** minimum-state DFA
 - Ignoring the particular names of states
- ▶ In other words
 - For every DFA, there is a unique DFA with minimum number of states that accepts the same language



Minimizing DFA: Hopcroft Reduction

▶ Intuition

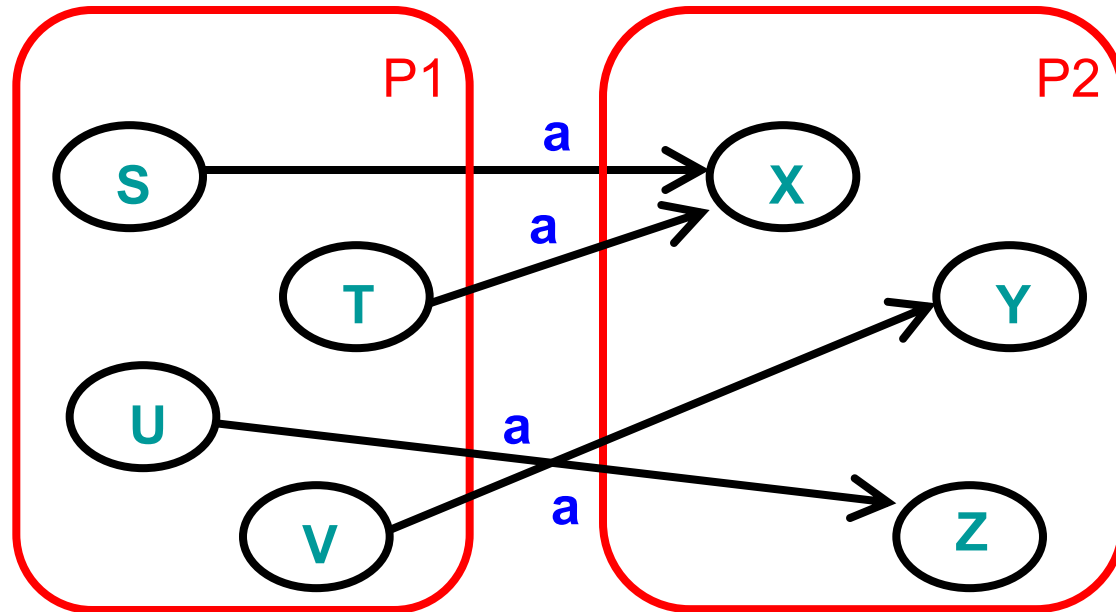
- Look to distinguish states from each other
 - End up in different accept / non-accept state with identical input

▶ Algorithm

- Construct initial partition
 - Accepting & non-accepting states
- Iteratively split partitions (until partitions remain fixed)
 - Split a partition if **members in partition have transitions to different partitions for same input**
 - Two states x, y belong in same partition if and only if for all symbols in Σ they transition to the same partition
- Update transitions & remove dead states

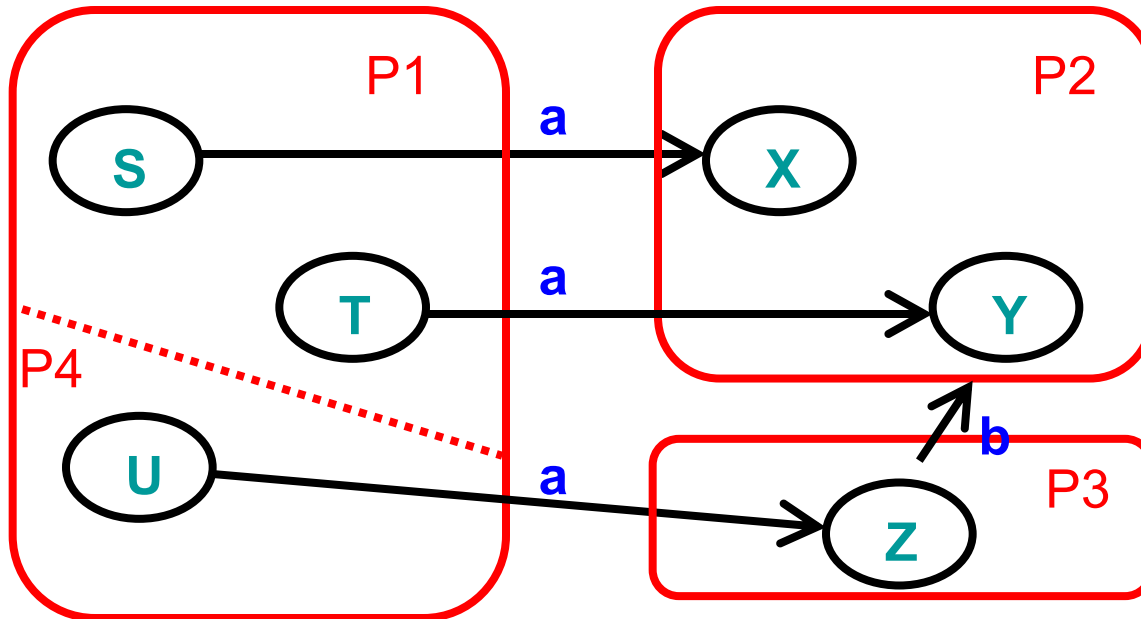
Splitting Partitions

- ▶ No need to split partition $\{S, T, U, V\}$
 - All transitions on a lead to identical partition $P2$
 - Even though transitions on a lead to different states



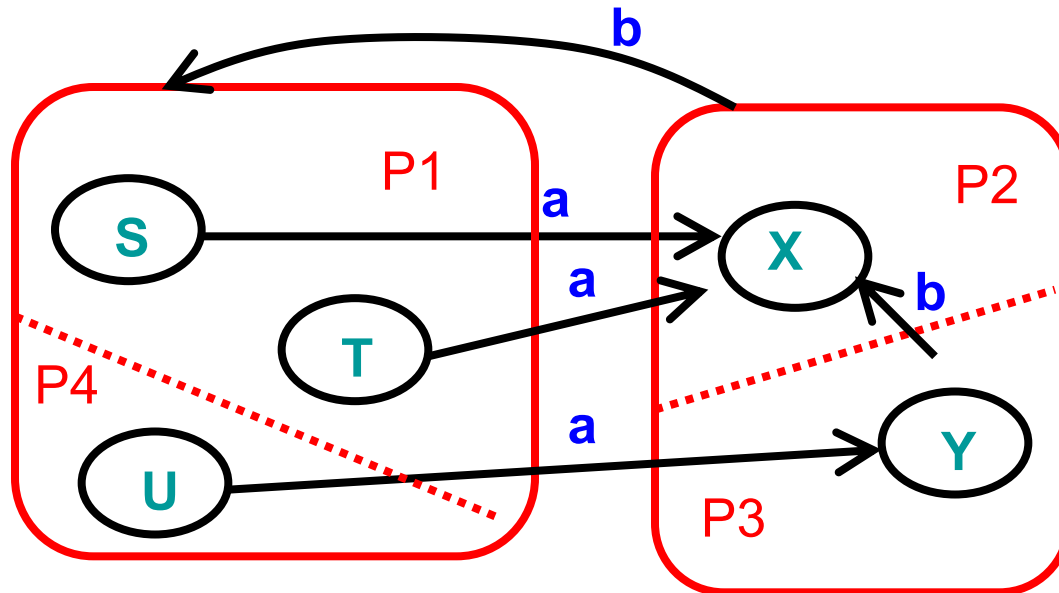
Splitting Partitions (cont.)

- ▶ Need to split partition $\{S, T, U\}$ into $\{S, T\}$, $\{U\}$
 - Transitions on a from S, T lead to partition $P2$
 - Transition on a from U lead to partition $P3$



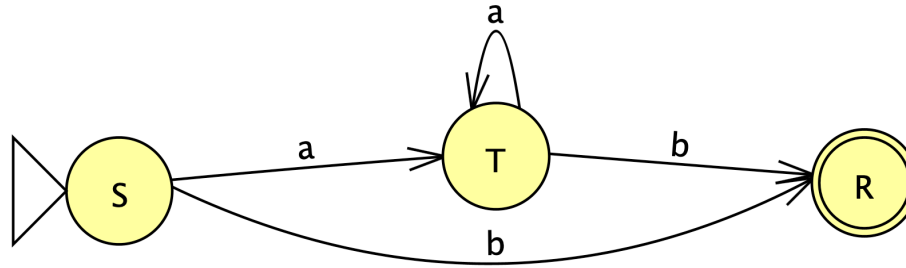
Resplitting Partitions

- ▶ Need to reexamine partitions after splits
 - Initially no need to split partition $\{S, T, U\}$
 - After splitting partition $\{X, Y\}$ into $\{X\}, \{Y\}$ we need to split partition $\{S, T, U\}$ into $\{S, T\}, \{U\}$



Minimizing DFA: Example 1

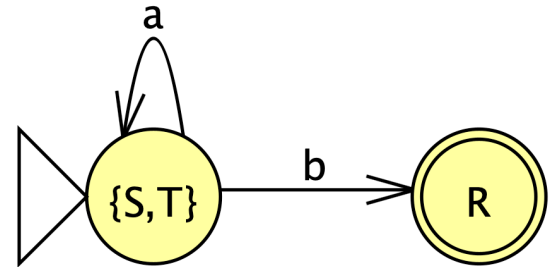
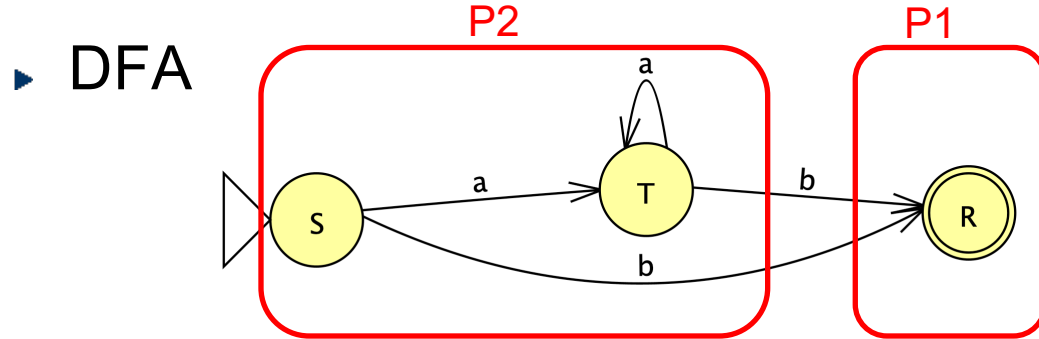
- ▶ DFA



- ▶ Initial partitions

- ▶ Split partition

Minimizing DFA: Example 1



▶ Initial partitions

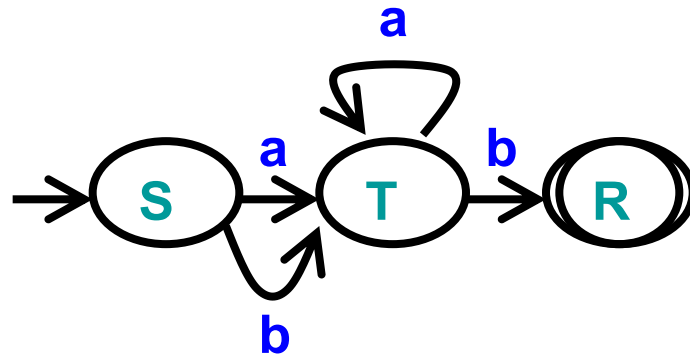
- Accept $\{ R \} = P1$
- Reject $\{ S, T \} = P2$

▶ Split partition?

→ Not required, minimization done

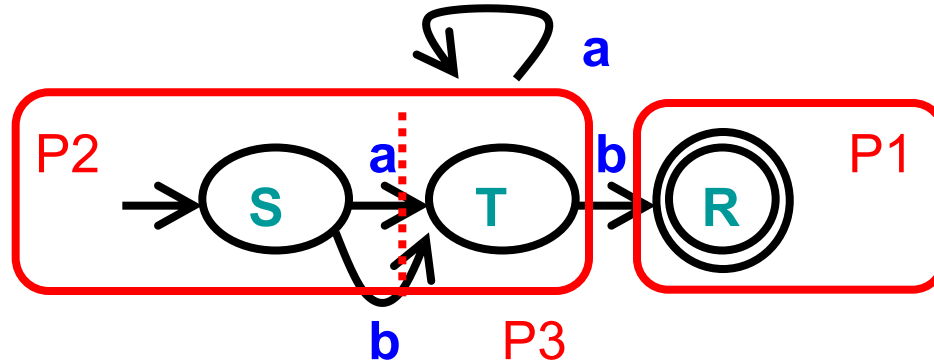
- $move(S, a) = T \in P2$
- $move(T, a) = T \in P2$
- $move(S, b) = R \in P1$
- $move(T, b) = R \in P1$

Minimizing DFA: Example 2



Minimizing DFA: Example 2

▶ DFA



▶ Initial partitions

- Accept $\{ R \} = P1$
- Reject $\{ S, T \} = P2$

DFA
already
minimal

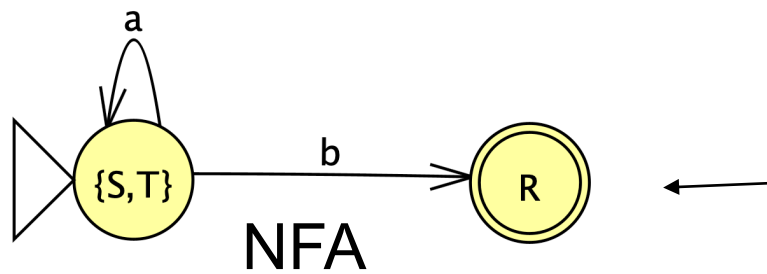
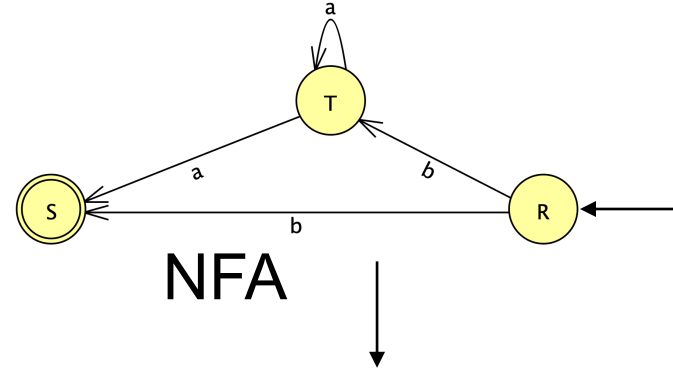
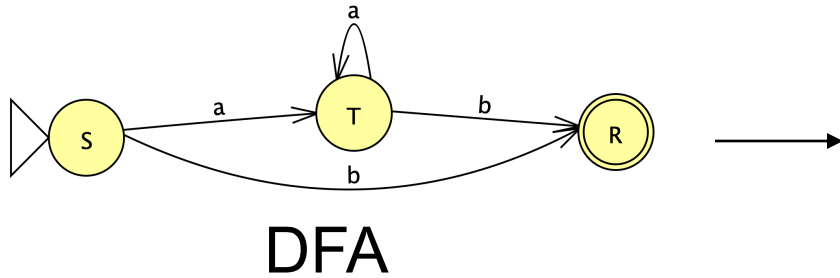
▶ Split partition? \rightarrow Yes, different partitions for B

- $\text{move}(S, a) = T \in P2$ – $\text{move}(S, b) = T \in P2$
- $\text{move}(T, a) = T \in P2$ – $\text{move}(T, b) = R \in P1$

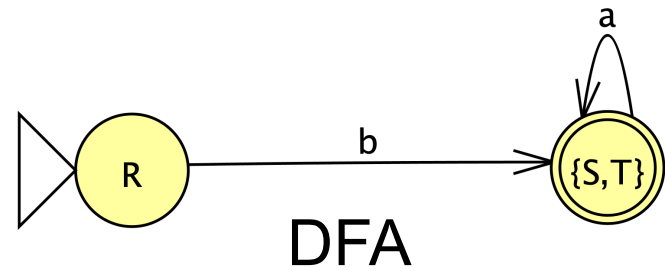
Brzowski's algorithm

1. Given a DFA, reverse all the edges, make the initial state an accept state, and the accept states initial, to get an NFA
2. NFA \rightarrow DFA
3. For the new DFA, reverse the edges (and initial-accept swap) get an NFA
4. NFA \rightarrow DFA

Brzowski's algorithm

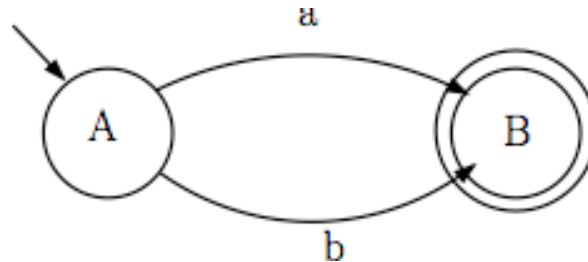


Minimum DFA



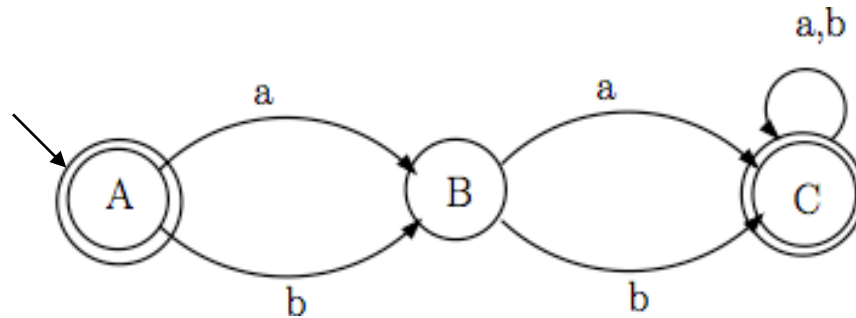
Complement of DFA

- ▶ Given a DFA accepting language L
 - How can we create a DFA accepting its complement?
 - Example DFA
 - $\Sigma = \{a,b\}$



Complement of DFA

- ▶ Algorithm
 - Add explicit transitions to a dead state
 - Change every accepting state to a non-accepting state & every non-accepting state to an accepting state
- ▶ Note this **only** works with DFAs
 - Why not with NFAs?



Summary of Regular Expression Theory

- ▶ Finite automata
 - DFA, NFA
- ▶ Equivalence of RE, NFA, DFA
 - RE \rightarrow NFA
 - Concatenation, union, closure
 - NFA \rightarrow DFA
 - ϵ -closure & subset algorithm
- ▶ DFA
 - Minimization, complementation